LECTURE 8: THE FORMATION OF BOUND STRUCTURES, HYDROSTATIC EQUILIBRIUM, AND DARK MATTER GALAXY FORMATION

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Note - there's more detail in these notes than covered in the lecture - please read them carefully

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I. Collapse and Violent Relaxation

We saw last time that if we had a tophat perturbation, the body of the perturbation collapsed all at the same time, and the surrounding material out to some r_{last} and corresponding m_{last} rain in on top of it it in some slowly tailing-off infall. A more realistic perturbation will have some central volume of roughly constant contrast which will collapse at roughly the same time, will in general not be so violent as the tophat case, but will not differ much in qualitative terms. As Aurelien will discuss next week, the power spectrum of perturbations on the small scales we are considering is roughly k^{-3} , which corresponds to roughly equal 'roughness' on all scales, so the tophat in the real universe will itself be pretty lumpy. These lumps will pull other lumps away from their purely radial orbits a little, so the mass will in fact not all bang into itself at the collapse time τ_c . Thus there will be some minimum size at about τ_c , but there will be lots of kinetic energy and the system will be very lumpy (because all the little lumps have grown during the collapse as well.) It will expand again, bounce around, and finally settle down to some equilibrium configuration. Computer simulations show that it is pretty settled in a short time, about $\tau_c/2$ after the initial collapse, so after a total elapsed time of about $3\tau_c/2$.

During these early phases, the system undergoes what is called *violent relaxation*—energy is exchanged between the particles in lumps on all scales, but it is the interaction of individual particles with lumps which is important during this phase. In a steady, equilibrium system made of stars and gas, the total energy of a particle, kinetic plus potential, is conserved, but in this violent phase, though the total energy of the *system* is conserved, the energy of individual particles is not. Instead, energy is exchanged rapidly. The energy of individual particles is not conserved whenever the gravitational *potential* Φ is changing, and in fact it can be shown that for an individual particle,

$$\frac{dE}{dt} = \frac{\partial \Phi}{\partial t}.\tag{1}$$

We saw last time that the collapse time scale of a structure collapsing due to gravity is $\pi\sqrt{r_{max}^3/2Gm} = \sqrt{3\pi/2G\rho}$, where ρ is the initial density. For example, the Hubble constant is the inverse of the timescale for expansion of the universe, and is of order $\sqrt{8\pi G\rho/3}$. When any self-gravitating system does something in response to its own gravity, this is always the timescale. (Just for fun, think about the orbital time of the earth, and show that it is of order $1/\sqrt{G\rho_m}$, where ρ_m is the density the sun would have if it were smeared out over a sphere whose radius is that of the earth's orbit). If the potential is changing on this timescale, the timescale of a particle orbit in the system, then particles

essentially forget their initial energy and initial velocities; they are scattered effectively both in velocity and energy.

The result of this is statistically rather interesting. During this phase a particle feels numerous little kicks in each component of velocity which are essentially statistically independent as it interacts with various lumps in the rapidly changing environment, and the total change in velocity is large enough that it forgets what its initial velocity was. There is a very powerful theorem in statistics, the Central Limit Theorem, which says that if some variable (say the x component of the velocity) is a sum of a very large number of statistically independent variables (the little changes) then the sum (the final velocity) has a probability distribution which is *normal*:

$$P(v_x) = \frac{1}{\sqrt{2\pi\sigma^2}} exp(-v_x^2/2\sigma^2), \tag{2}$$

the classical 'bell curve'. Here the $variance\ \sigma^2$ of the distribution is the square root of the sum of the mean squares of the kicks in velocity it got along the way. In our example, the mean kick is assumed to be zero, which it must be under the assumption of spherical symmetry; if it is not, the quantity in the numerator in the exponent is $-(v_x - \bar{v}_x)^2$, and \bar{v}_x is the mean x-velocity, which is the sum of the mean of the kicks. The quantity σ is called the dispersion or, more correctly the standard deviation, and is often referred to as if 'sigma' was its name—a value which lies three standard deviations from the mean is referred to as a '3-sigma' point. The multiplier, $1/\sqrt{2\pi\sigma^2}$ is just to make the integral (probablity that v_x has some value) unity. Physicists and astronomers do not use the term 'normal', though everybody else in the world does; they instead call this a 'gaussian' distribution, but they mean the same thing. So we can expect the velocity distribution of our final object to be roughly gaussian or normal.

II. Hydrostatic Equilibrium

What is its density distribution like once it settles down? To think about this, we need to consider the general equation which describes a system which has established an equilibrium with its own self-gravity and internal motions.

What are the forces in such a system? First, there is gravity. The potential energy w of a particle of mass m in a gravitational field is $m\Phi$ (indeed, this is the *definition* of the potential Φ); the potential Φ in a spherical system outside the mass is just, of course, GM/r, where M is the mass of the *system*. The *force* is just the negative of the gradient of the potential energy because the work done in moving a particle from \mathbf{x} to $\mathbf{x} + \mathbf{dx}$ is just the change in potential energy:

work =
$$-dw$$
 = force $\cdot dx$,

or

force =
$$-dw/dx = -md\Phi/dx$$

Where we have written things as if they dependended on only one variable x; in three dimensions, this becomes, clearly

force =
$$\mathbf{f} = -m\nabla\Phi$$
.

So suppose the final system is spherical, and consider a little volume element oriented so that it has faces perpendicular to the radius, has thickness dr in the radial direction, and has faces of area A. The density in the volume is ρ , so the mass is $dm = \rho A dr$, and the gravitational force on the mass in the volume is radial and is $-dm \cdot d\Phi/dr = -dm \cdot GM_r/r^2$, where M_r is the mass contained within r. The system is in equilibrium by assumption, so the mean radial velocity of particles in the box must be zero. If not, the body would either be expanding or contracting. In general, the velocity of particles at some point in the body can be broken down into two parts:

$$\mathbf{v} = \bar{\mathbf{v}} + \mathbf{u},\tag{3}$$

where $\bar{\mathbf{v}}$ is the mean velocity in a small region surrounding the point, and \mathbf{u} is the difference from the mean. \mathbf{u} is called the *peculiar*, or random, velocity. In our spherical example, $\bar{\mathbf{v}} = 0$. The peculiar velocities exert forces in the system called pressure forces. To see this, imagine replacing the imaginary faces of our volume with perfect reflecting surfaces. The particles bouncing off these faces clearly exert a force on the face, but since the mean velocity of the particles is zero at the face, inserting the reflecting face can in no way alter the physics of the problem. What is the force? The particles hit the face at a rate $An(u_r)u_rdu_r$, where $n(u_r)du_r$ is the number density of particles at u_r in du_r . The change in momentum of each particle when it hits the face is $2mu_r$. The rate of change of momentum is the force, so for the particles of peculiar velocity u_r the force is $df = 2n(u_r)mu_r^2du_r$. If we are looking at the lower face, we are only interested in particles with positive u_r , because they are the only ones which hit the face. So the total force is

$$f_r = 2A \int_{(u_r > 0)} mn(u_r) u_r^2 du_r = A \int mn(u_r) u_r^2 du_r,$$

where in the last expression we recognize that we are integrating only over half the particles (the upward-moving ones), but that just cancels the factor of 2 in front. But the particle mass times the number density is just the mass density ρ . So we can write

$$f_r = A\rho \bar{u_r^2} = A\rho \sigma_r^2$$

The quantity σ_r is called the *radial velocity dispersion*, and the product with density ρ is called the *pressure*. If the system contains particles with different masses and different velocity distributions, this is more complex, but you get the idea. Now the box must neither rise nor fall, (more accurately, be accelerated neither up nor down) which means that the gravitational force on the box must just be balanced by the pressure difference on its faces:

$$-\rho A dr d\Phi/dr = -\rho G M_r/r^2 A dr = A dP$$

$$\frac{dP}{dr} = \frac{d(\rho\sigma^2)}{dr} = -\rho G M_r / r^2 \tag{4}$$

This is called the hydrostatic equation for spherical geometry. If the system is not spherical, then the general form of this is more complex and involves the mean velocity as well (rotation, for example, develops centripetal accelerations, and in a rotatating system the mean velocity is not, of course, zero, even though the system is not changing in time) but this will serve us for the moment. This development is the same for a gas, in which the pressure is a familiar concept, and for a system of stars or dark matter particles. The physical difference is profound; in a gas there are lots of collisions, so it does not make much sense to talk about the *orbit* of a gas particle, and the pressure is very intuitive. In a stellar system or a system of dark matter particles, there are essentially no collisions, and particles are in independent orbits, but the hydrostatic equation is the same, as is the definition of the pressure. A system such as we are thinking about, in which the mean velocity is everywhere either zero or contributes negligibly to the forces, is called pressure supported and is referred to as a hot system, which has nothing to do with ordinary temperature but does, as in the ordinary thermal case, refer to large random particle velocities. In the opposite limit, in which, all the particles are in regular circular orbits in a disk about the center of mass of the system, all the velocity is mean or bulk velocity and there is no peculiar or random velocity. These systems are called rotationally supported and are referred to as *cold* systems.

III. The Virial Theorem

For systems in hydrostatic equilibrium, such as stars or galaxies or planets or clusters, there is an important and simple relation among the various kinds of energy in the system which enables us to do simple calculations of their properties. To see where this comes from, we consider again a spherical system, though the result is quite general. For each particle in the system, we can write Newton's second law as

$$m\ddot{\mathbf{x}} = -m\nabla\Phi = m\mathbf{g}.\tag{5}$$

Here **g** is the gravitational acceleration, which is radial, inward, and has magnitude GM_r/r^2 . If we dot this relation with the position vector **x**, we get

$$m\mathbf{x} \cdot \ddot{\mathbf{x}} = -m\mathbf{x} \cdot \nabla \Phi = -mGM_r/r.$$

The last term on the right comes from multiplying the radial component of \mathbf{x} , which is r, by the expression for the gravitional force. Now you can easily verify that

$$d^2\mathbf{x}^2/dt^2 = 2\mathbf{x} \cdot \ddot{\mathbf{x}} + 2(\dot{\mathbf{x}})^2,$$

so we can write

$$\frac{d^2}{dt^2} \left(\frac{m\mathbf{x}^2}{2} \right) - m(\dot{\mathbf{x}})^2 = -\frac{mGM_r}{r}.$$
 (6)

Let us now sum over all the particles in the system. Then Equation (6) becomes

$$\frac{1}{2}\frac{d^2}{dt^2}\int \rho \mathbf{x}^2 dV - 2T = W,\tag{7}$$

Where we have replaced in the first term the sum over all particles by the integral of the ρdV , which is clearly equivalent if we have lots of particles. The sum over the second term in Equation (6) is clearly the total kinetic energy T of the system, and the RHS the total gravitational energy W of the system. If the system is in equilibrium, its shape and density distribution are not changing, so the first term, which is just the second time derivative of the moment of intertia, vanishes. This is strictly only true for systems of very large numbers of particles; for smaller systems one needs both to sum over particles and average over time, but the result is the same:

$$2T + W = 0 (8)$$

which holds instantaneously for systems with very large numbers of particles, and in time average for any bound system in equilibrium. This is called the *virial theorem*. We have derived it for spherical systems, but it is, in fact, true for any equilibrium system; the only difficulty in the general derivation is some algebraic messiness in the potential energy term, the biggest problem being convincing oneself that the term obtained actually *is* the potential energy and some bookkeeping worries about double counting, etc. Look at a book if you are interested. In the general case, it is often useful to separate the velocity into the average (bulk) velocity and the peculiar velocity, as in Equation (3); when we do this, the virial theorem becomes

$$2T_{av} + 3P_{tot} + W = 0 (9)$$

for the case in which the velocity distribution is *isotropic*, so $\sigma_x^2 = \sigma_y^2 = \sigma_z^2$, and here T_{av} is the kinetic energy associated with the mean velocity and P_{tot} the integral of the pressure over the volume of the system:

$$T_{av} = \frac{1}{2} \int \rho \bar{v}^2 dV$$
$$P_{tot} = \int P dV$$

This provides a way of calculating the kinetic energy of the system without having to worry about the details of the motion of individual particles; only the mean velocity and the pressure appear. Why is there no cross term when you square the velocity of Equation (3) and sum everything up???

To see how one might use this relation, ask a question. Suppose we have some system of mass M with some velocity dispersion σ . Roughly how big is it when it is in equilibrium? The gravitational energy of each particle is $-GmM/\bar{r}$, where \bar{r} is some average radius of the particle in its orbit, so it must be that the gravitational energy of the *system* is, just summing over the particle masses, $W = -GM^2/R_g$, where R_g is some average of the

radii over the particle orbits of all the particles. The quantity R_g is clearly a reasonable measure of the size of the system, and is called the gravitational radius for obvious reasons. The kinetic energy is, if the velocity dispersion σ is reasonably constant over the system, $T = 1/2M\sigma^2$, so the virial theorem says

$$M\sigma^2 = \frac{GM^2}{R_g}$$

or

$$R_g = \frac{GM}{\sigma^2}$$

Now it is a happy coincidence that there is a very close but essentially coincidental relation between the gravitational radius and the so-called 'half-mass' radius $R_{1/2}$, the radius containing half the mass of the system, which is usually much easier to compute than R_g and is a much more intuitive notion of the size of a system. Over a very large range in density distributions, from uniform spheres, exponential spheres, power laws, etc, etc, the relation

$$R_g \approx 2R_{1/2}$$

holds to an accuracy of about ten percent, and better for realistic density distributions. Notice that for a system in equilibrium the *total energy*, sometimes called the *binding energy*, is negative and since E = T + W, 2T + W = 0, it must be that

$$E = -T = \frac{W}{2}$$

IV. The Dark Matter: Isothermal Spheres

After the collapse and violent relaxation, the dark matter in a body which forms out of the fluctuations in the early universe does not change much unless it merges with another. The baryonic matter can do interesting and wonderful things like make stars and planets and people, but the dark matter particles can only move in their more-or-less original orbits. We do not see the dark matter directly, but know it is there and can measure its gravitational effect. How do we do this?

First of all, what forms do we expect the dark matter to take—that is what are the *shapes* of the density distributions? Remember that we expected the velocity distribution to be roughly normal and for all particles to have roughly the same velocity dispersion. If we look at the equation of hydrostatic equibilibrium, we thus have, approximately,

$$\frac{dP}{dr} = \frac{d(\rho\sigma^2)}{dr}
= \sigma^2 \frac{d\rho}{dr} = \frac{-G\rho M_r}{r^2}$$
(10)

Can we find a simple solution for this equation? Let us look for a power law. Since we know that the hydrostatic equation requires a *decreasing* density with radius, look at solutions of the form $\rho = \rho_0 (r/r_0)^{-\alpha}$. If this the density, the contained mass M_r is

$$M_r = \int_0^r dm$$

$$= \rho_0 \int_0^r \left(\frac{r'}{r_0}\right)^{-\alpha} 4\pi r'^2 dr'$$

$$= 4\pi \rho_0 r_0^3 \frac{1}{3-\alpha} \left(\frac{r}{r_0}\right)^{3-\alpha}.$$
(11)

Note that this is not correct if $\alpha \geq = 3$, in which case the mass is divergent as one approaches r = 0, and no power law is both well behaved at the origin and contains finite mass as $r \to \infty$. We will see whether there is a satisfactory solution for Equation (10). Substituting our expression for ρ and the expression (2) for M_r into the hydrostatic equation, we get

$$-\alpha \sigma^2 \rho_0 r_0^{-1} \left(\frac{r}{r_0}\right)^{-\alpha - 1} = \frac{-4\pi G \rho_0^2 r_0}{3 - \alpha} \left(\frac{r}{r_0}\right)^{1 - 2\alpha}$$

Since the powers of r have to be the same on both sides,

$$1 - 2\alpha = -\alpha - 1,$$

or $\alpha = 2$, and

$$\sigma^{2} = 2\pi G \rho_{0} r_{0}^{2}$$

$$M_{r} = 4\pi \rho_{0} r_{0}^{2} r$$

$$= 2\sigma^{2} r/G$$

$$\rho = \sigma^{2}/2\pi G r^{2}$$
(12)

Notice that the *density* goes to infinity at the origin, but it is an integrable singularity and the contained mass is proportional to the radius all the way to the origin. This solution is called the *singular isothermal sphere*. If we demand that the density be finite at the origin, we discover that it falls slowly at first, approximately like $\rho = \rho_c \left[1 + (r/r_c)^2\right]^{-1}$, reaching about half its central value ρ_c at the *core radius* $r_c = 3\sigma^2/(2\pi G\rho_c)$. Thereafter it wiggles a bit and settles down to the behavior of the singular model.

Before we leave the isothermal sphere, let us ask a simple question. Suppose we have a test particle in a circular orbit of radius r about the center of the structure. Then the mass contained within r is $2\sigma^2 r/G$. In a circular orbit, the centripetal acceleration just balances the gravitational force, so the circular velocity v_c is

$$\frac{v_c^2}{r} = GM_r/r^2$$

$$v_c^2 = GM_r/r$$

$$= 2\sigma^2$$

$$v_c = \sqrt{2}\sigma$$
(13)

and is *constant* with radius. Thus if we can measure the circular velocity of some test particles in a dark matter isothermal halo, we can determine the velocity dispersion in the halo and, if the circular velocity is constant, demonstrate that it is approximately isothermal. This is a very powerful result.

We have seen that the continued infall keeps adding material to the object we have formed; in a future problem set you will show that this material forms a halo with a density distribution which is approximately $\rho \propto r^{-9/4}$, only trivially different from the expected r^{-2} in the central parts. This will cut off quite sharply as the last bound shell is approached. Let us now think about the dynamics of the final object. How can we connect the present quantities (velocity dispersion, size) of the object with its properties before it formed and indeed with its initial conditions?

V. Dynamics Before and After Collapse

Consider the perturbation near the epoch of maximum expansion. It is approximately a uniform sphere, and you will show in the problem set that its gravitational energy (which is its total energy, because it has no kinetic energy at that epoch) is

$$E = -\frac{3GM^2}{5R_{max}}.$$

After it has collapsed and stabilized (we use the term *virialized*, which means that it has settled enough to satisfy the virial theorem), we have E = -T = W/2

$$E = \frac{GM^2}{2R_g} \approx \frac{GM^2}{4R_{1/2}}.$$

Thus the half-mass radius of the final configuration is, roughly,

$$R_{1/2} \approx \frac{5}{12} R_{max} \approx 0.4 R_{max}$$

So the final dark matter configuration is roughly *half* the size at maximum expansion. If we can determine any two of the half-mass radius, the mass, or the velocity dispersion, we can determine a great deal about the perturbation that made the system, since these three quantities are related by

$$T = \frac{3M\bar{\sigma}^2}{2} = |E| \approx \frac{GM^2}{4R_{1/2}},$$

or

$$\bar{\sigma}^2 = \frac{GM}{6R_{1/2}}$$

so we can, having $R_{1/2}$, get $R_{max} \approx 2.5 R_{1/2}$, and thus determine the collapse time

$$\tau_c = \pi \left(\frac{R_{max}^3}{2GM}\right)^{1/2}$$

$$\approx 8.2 \left(\frac{R_{1/2}^3}{GM}\right)^{1/2}$$

$$\approx 3.3 \frac{R_{1/2}}{\bar{\sigma}}$$

Notice that the last line of this says that the collapse time is of order the average travel time across the body. Given τ_c , the amplitude of the perturbation can be calculated from the relation we developed last time,

$$\tau_c = \frac{\pi}{H_i} \left(\delta^+ \right)^{-3/2}$$

For our Galaxy, the central value of σ is about 160 km/sec, as deduced from the rotation velocity of about 220 km/sec. This value of σ corresponds to a mass of about $10^{10} M_{\odot}$ per kpc of radius (Equation (12)). We believe that the total mass of the Galaxy is about $10^{12} M_{\odot}$, so the radius extends to something like 100 kpc, but we do not know exactly what the form of the cutoff is like. The cutoff can *happen* only if the dark matter is colder in the outer parts, so the mean σ will be less than the central value. If we do not worry about this too much, take a mean σ of, say 100 km/sec and a half-mass radius of 50 kpc, we get a collapse time of about 1.7×10^9 years, about 7 rotation periods of the Galaxy. The velocities in the collapse near the end must be near the circular velocity, about 200 km/sec.

VI. Angular Momentum

We have seen that gravity causes perturbations to grow, but in the absence of gravity perturbations in velocity die away very quickly. You can use the reflecting box trick to show that peculiar velocities are proportional to 1/R as the universe expands; all momenta vary thus, and this is another way to get the redshift relation, since the energy of photons is proportional to their momentum. Now angular momentum is a radius times a velocity, so since radii go like R and velocities like 1/R, angular momentum is conserved in the expansion. Cool. Spiral galaxies are typically rotating at 200-300 km/sec today, and a galaxy like the Milky Way has most of its baryonic mass, about $10^{11} M_{\odot}$ contained within about 10 kpc radius, which corresponds to a baryon density of about $(10^{11} * 2 \times 10^{33})g/[(4\pi/3)*(3\times 10^{22}cm)^3] = \approx 2\times 10^{-23}g/cm^3$. At recombination, the total density was about $3\times 10^{-21}g/cm^3$ and the baryon density about a tenth of that, say 3×10^{-22} , about a factor of ten higher than the mean spherical density in a spiral galaxy at the present epoch. Thus the mass was contained in a radius smaller by the cube root of 10, about a factor of two, and the velocities thus a factor of two higher, say 500 km/sec. Velocities this high, 1.5×10^{-3} of the velocity of light, would result in fluctuations in the

microwave background of this same size, and these are not observed. If one goes back even farther into the past, one soon runs into relativistic velocities, which are clearly at variance with inflation (as are *any* appreciable peculiar velocities), and almost certainly at odds with primordial nucleosynthesis, the exact thermal nature of the background, and many other things. Conserved angular momentum, also, inflates away just as conserved baryon number does in the inflationary scenario, but the observations rule out enough angular momentum early in the universe to explain galaxies even if one does not believe inflation. It seems clear that the rotation does *not* arise from conserved angular momentum from the early universe. Where else can rotation come from?

Like energy, angular momentum is conserved in the large, but can be exchanged between structures. Consider two nearby tophat perturbations in the universe, neither one completely spherical and aligned randomly with respect to one another. For the sake of argument assume that they are ellipsoids. Then since gravity is a $1/r^2$ force, the *tidal force* exerts a torque on both—the nearer bulge is pulled harder than the farther one, and harder than the center. So relative to the center, the nearer bulge is attracted and the farther is repelled—the mechanism is precisely the same as the tides on the earth, but here we have an intrinsically nonspherical shape. The angular momentum is the torque times the time, and since the shape of the perturbations do not change very much while they are in the linear regime, it is changing the angular momentum in a progressive, steady manner. We could easily estimate the effect knowing what we know, but there is not really time. What we can do is figure out how we might characterize it.

How might we characterize the importance of rotation? Dynamically, that is. One measure is clearly how much *kinetic energy* is associated with rotation versus the total; we can make a dimensionless measure of this by setting a parameter λ

$$\lambda^2 = CT_{rot}/T_{tot} \approx \frac{C}{3} \frac{v_{rot}^2}{\sigma^2} \tag{14}$$

Where C is some number of order unity we can choose later for our convenience, and v_{rot} is some mean rotation velocity. Now from the virial theorem, T_{tot} is the binding energy of the structure, |E|, and T_{rot} is $Mv_{rot}^2/2$, where v_{rot} is some mean rotation velocity. The angular momentum $J = MRv_{rot}$, where R is some measure of the size of the object. Thus

$$\lambda^2 = \frac{C}{2} \frac{J^2}{MR^2|E|}$$

But $E \approx -GM^2/4R$, $R \approx GM^2/4|E|$, so

$$\lambda = 2\sqrt{2C} \frac{J\sqrt{|E|}}{GM^{5/2}}. (15)$$

If we take $2\sqrt{2C} = 1$, $C \approx 1/8$, this is actually the usual definition of λ . The quantity λ , which is called the angular momentum parameter, is thus approximately 0.4 for a cold disk ($T_{rot} = T_{tot}$ and is zero for a nonrotating spherical, pressure supported object. How

big can we get λ from tidal torques during the formation of structure? It is not hard to see that the effect of the torquing is pretty small on average—the structures as they grow are probably not long, thin bars or dumbbells, which you need to transfer angular momentum efficiently; the near bulge is not that much closer to the other perturbation than the far one, it is unlikely that the major axes of the shapes are at 45 degrees to the separation, which one needs for most efficient transfer, etc., etc. Both reasonable rough estimates and numerical experiments indicate that, on average, λ is about 0.05, with a large statistical spread, independent statistically of the details of the power spectrum or anything else that has been thought about. It is certainly not big enough to explain disks; with the value of C indicated, the value of lambda for a cold disk is about 0.4; we are short by something like a factor of 8 in rotation velocity and 60 in energy. But spiral disk galaxies are very common, and in fact most galaxies are disks. So the rotation of galaxies is not primordial and apparently cannot be produced by gravitational torques during formation. But wait we see the fast rotation and thin disks in the baryons, not in the dark matter. Might this be something we should think about? The week after next we will discuss what the baryons do, which, fortunately, can be much more exciting and interesting than what the dark matter does.