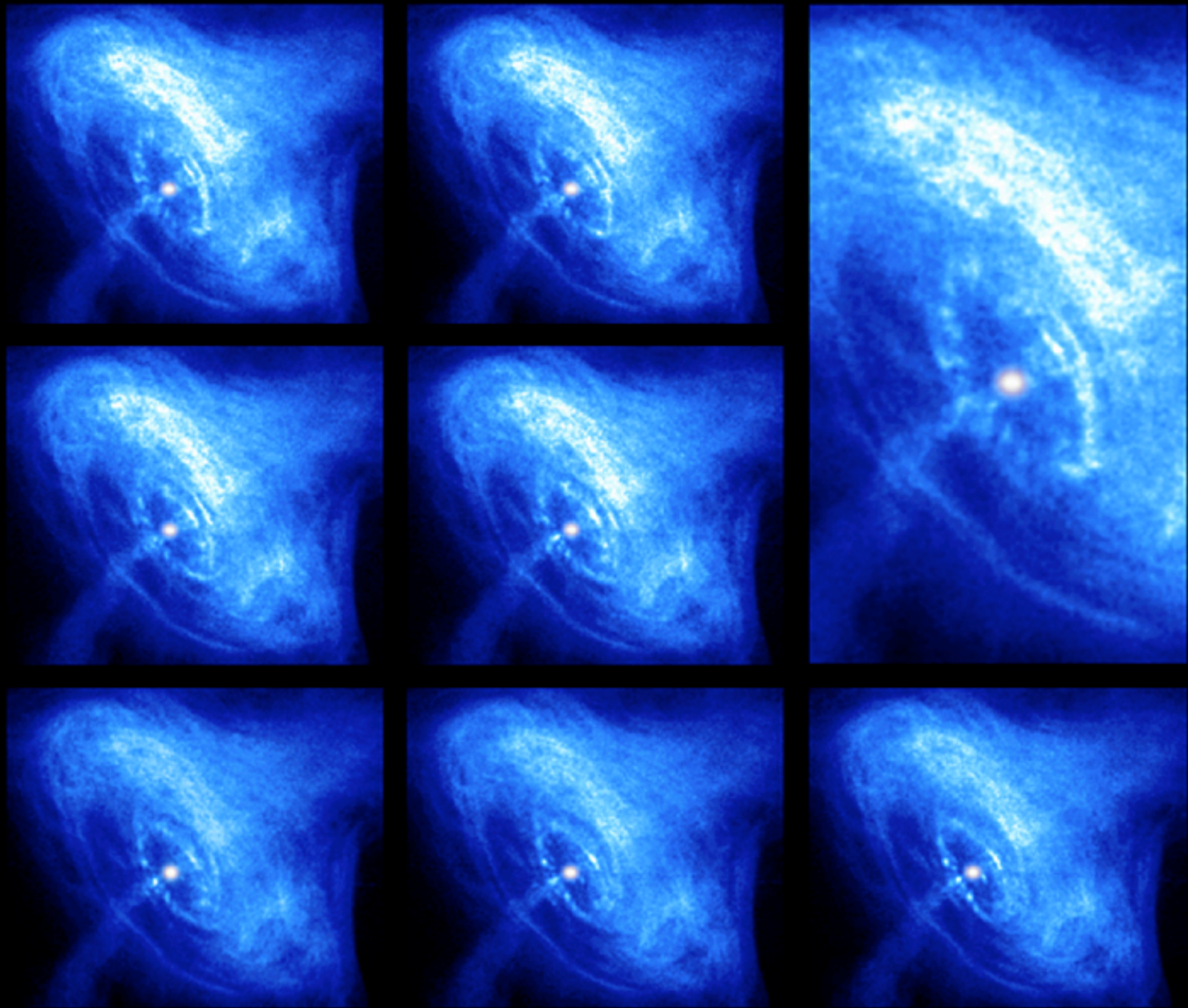


The 3D structure of the pulsar magnetosphere

Ioannis Contopoulos, Academy of Athens

Outline

- ✦ The aligned rotator
 - ✦ Smooth crossing of the light cylinder
 - ✦ Singular magnetospheric current
- ✦ The 3D rotator
 - ✦ Relativistic MHD on a desktop PC
- ✦ Prospects for the future



The aligned rotator

- Steady-state force-free axisymmetric relativistic MHD
Scharleman & Wagoner 1973

$$0 = \nabla \times B - 4\pi J \qquad \nabla \cdot B = 0$$

$$0 = -\nabla \times E \qquad E \cdot B = 0$$

$$\rho_e E + J \times B = 0$$

$$(1 - x^2) \left(\frac{\partial^2 \Psi}{\partial x^2} - \frac{1}{x} \frac{\partial \Psi}{\partial x} + \frac{\partial^2 \Psi}{\partial z^2} \right) - 2x \frac{\partial \Psi}{\partial x} = -AA'$$

The aligned rotator

- Regularization condition at $x=1$: $2B_z = AA'$
- Yields THE poloidal electric current distribution $A(\Psi)$
- Space charge density: $\rho_e = \frac{\Omega}{4\pi c} \frac{-2B_z + AA'}{1-x^2}$

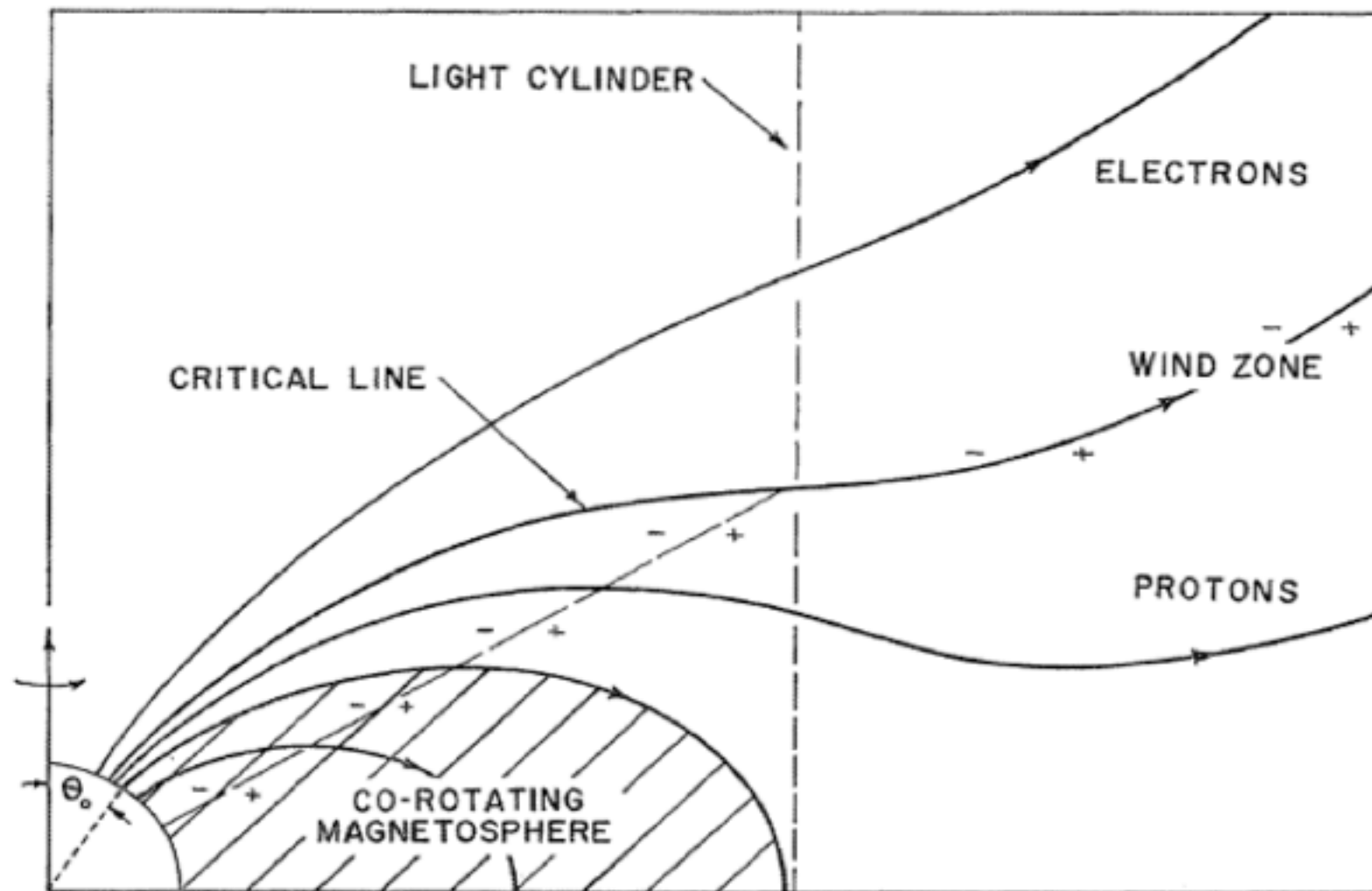
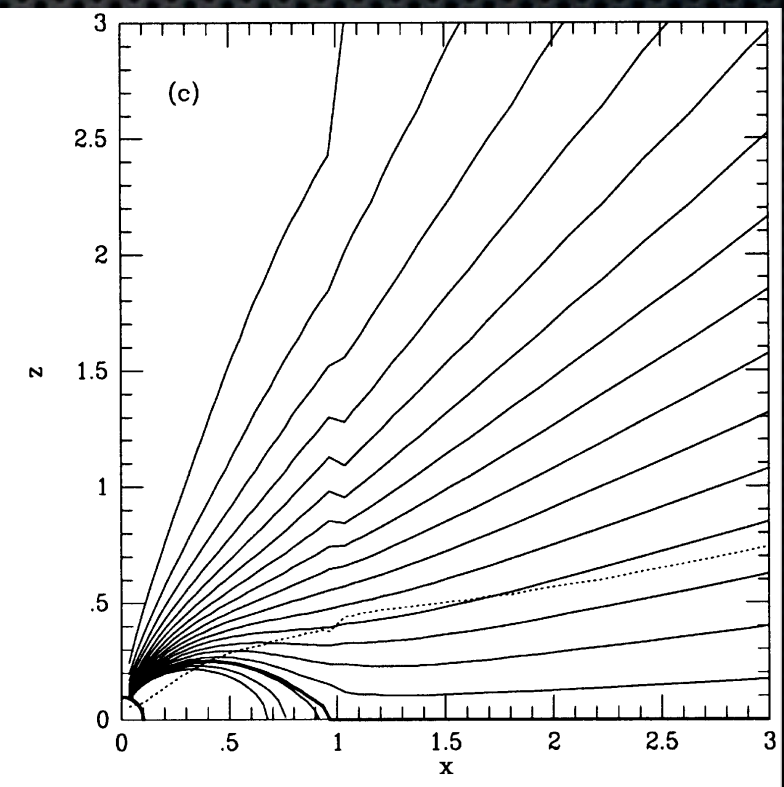
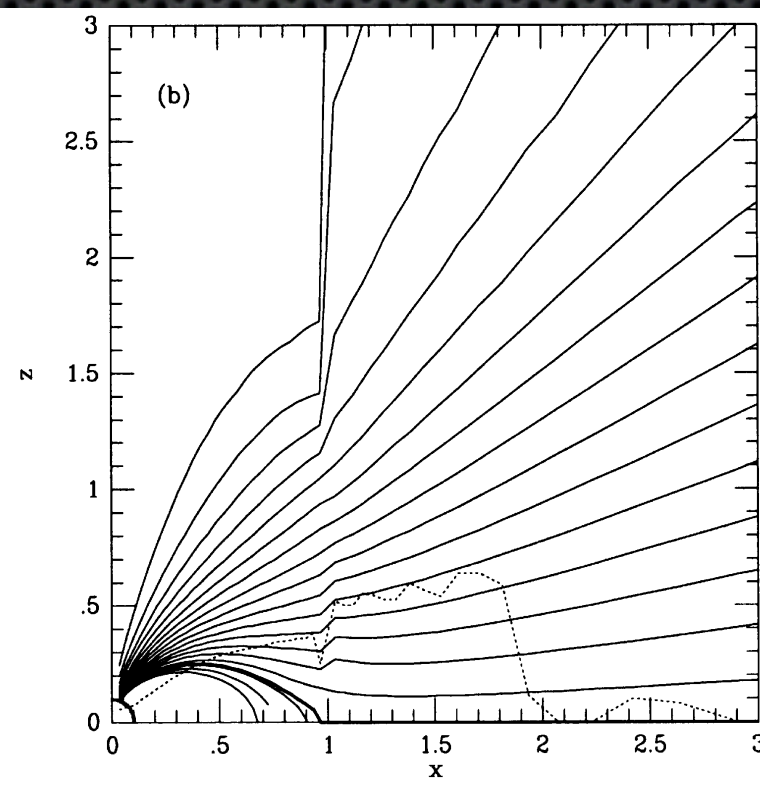
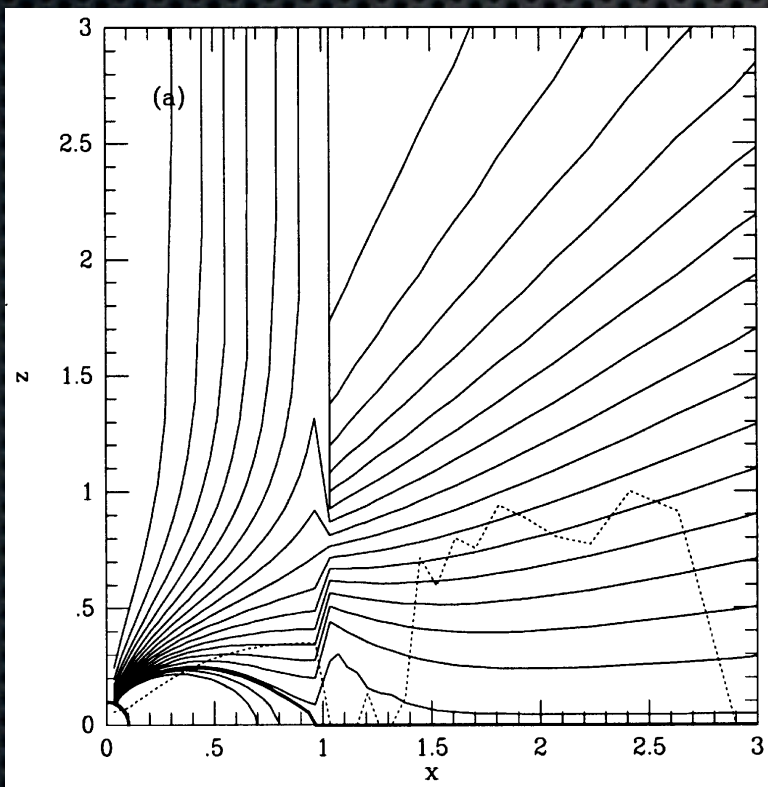
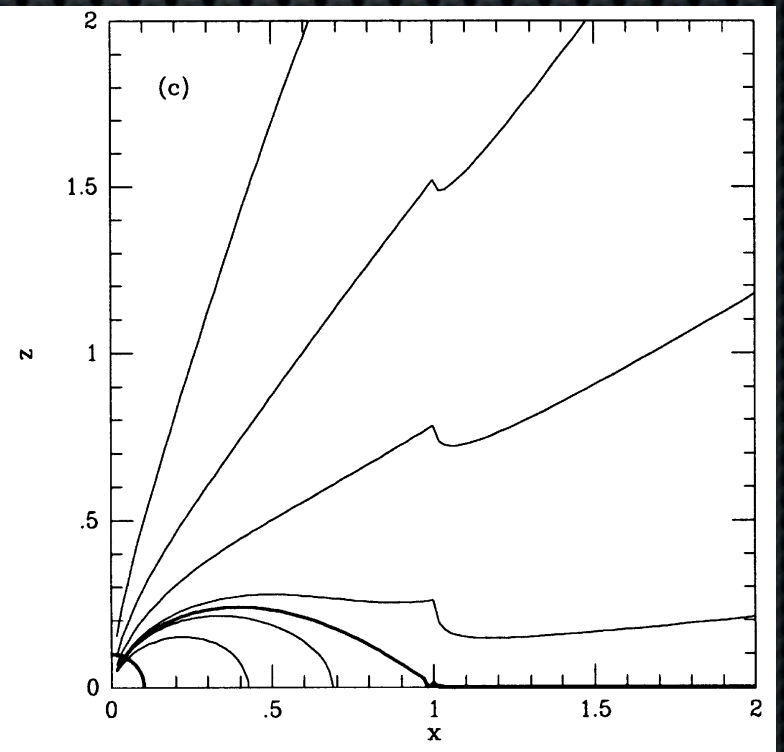
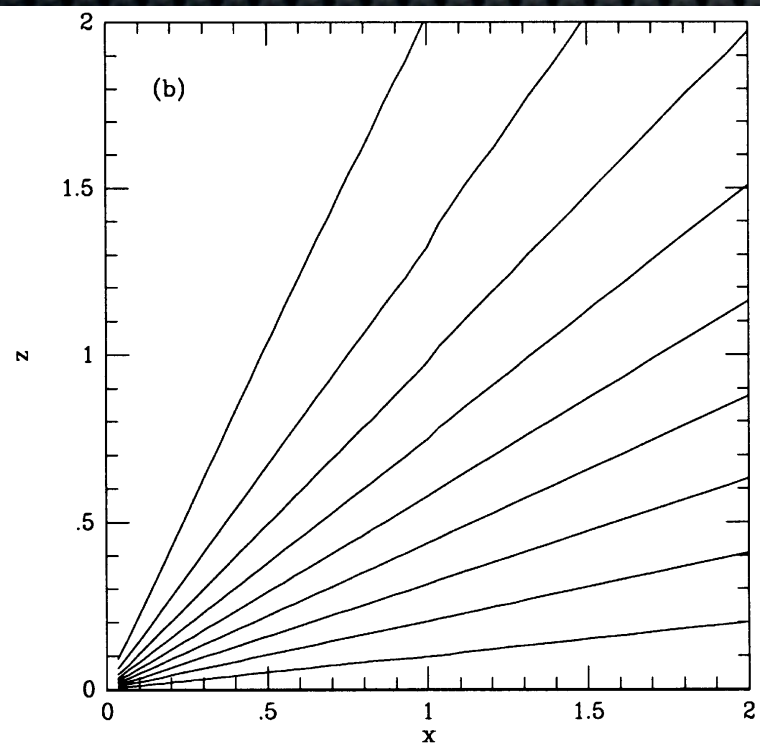
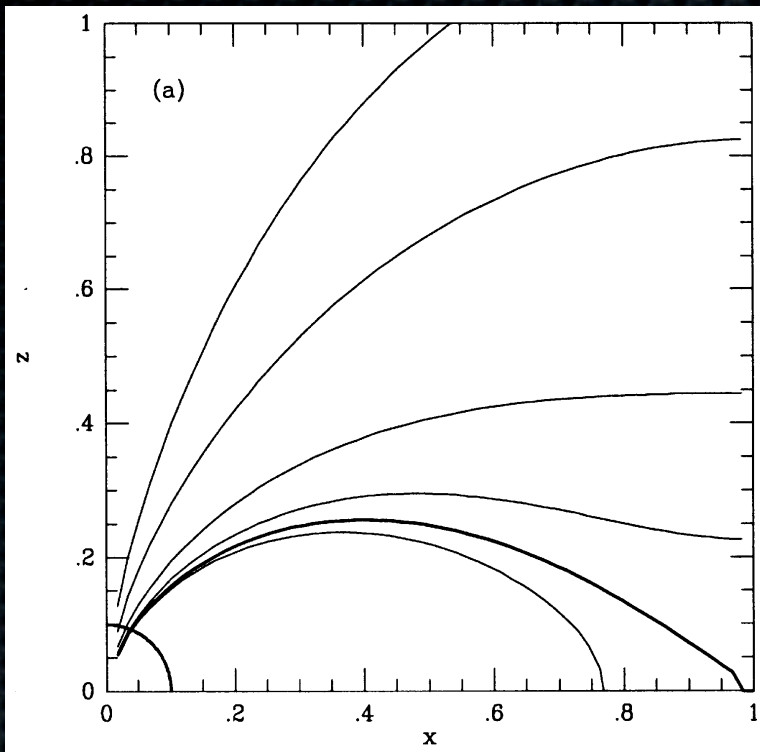
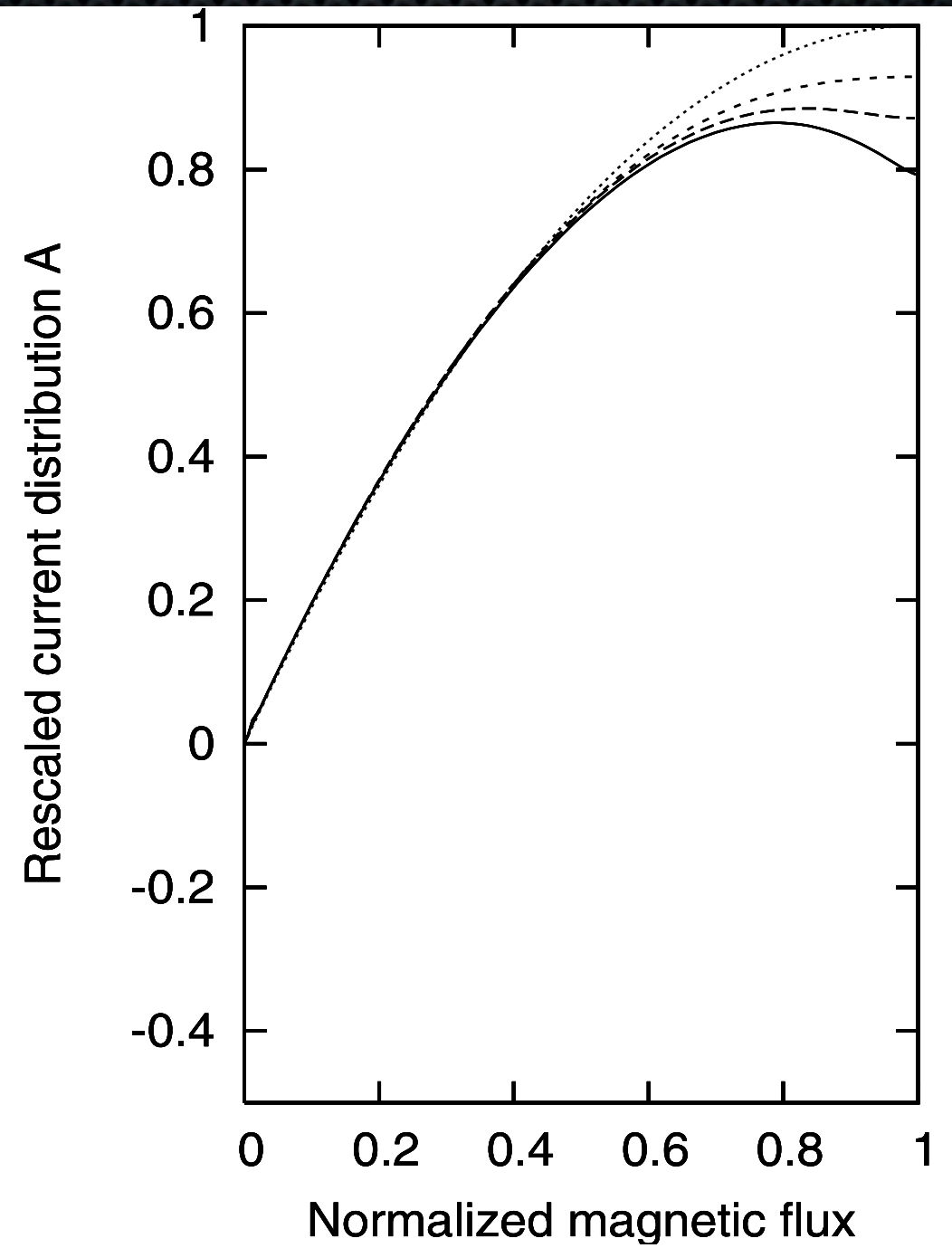
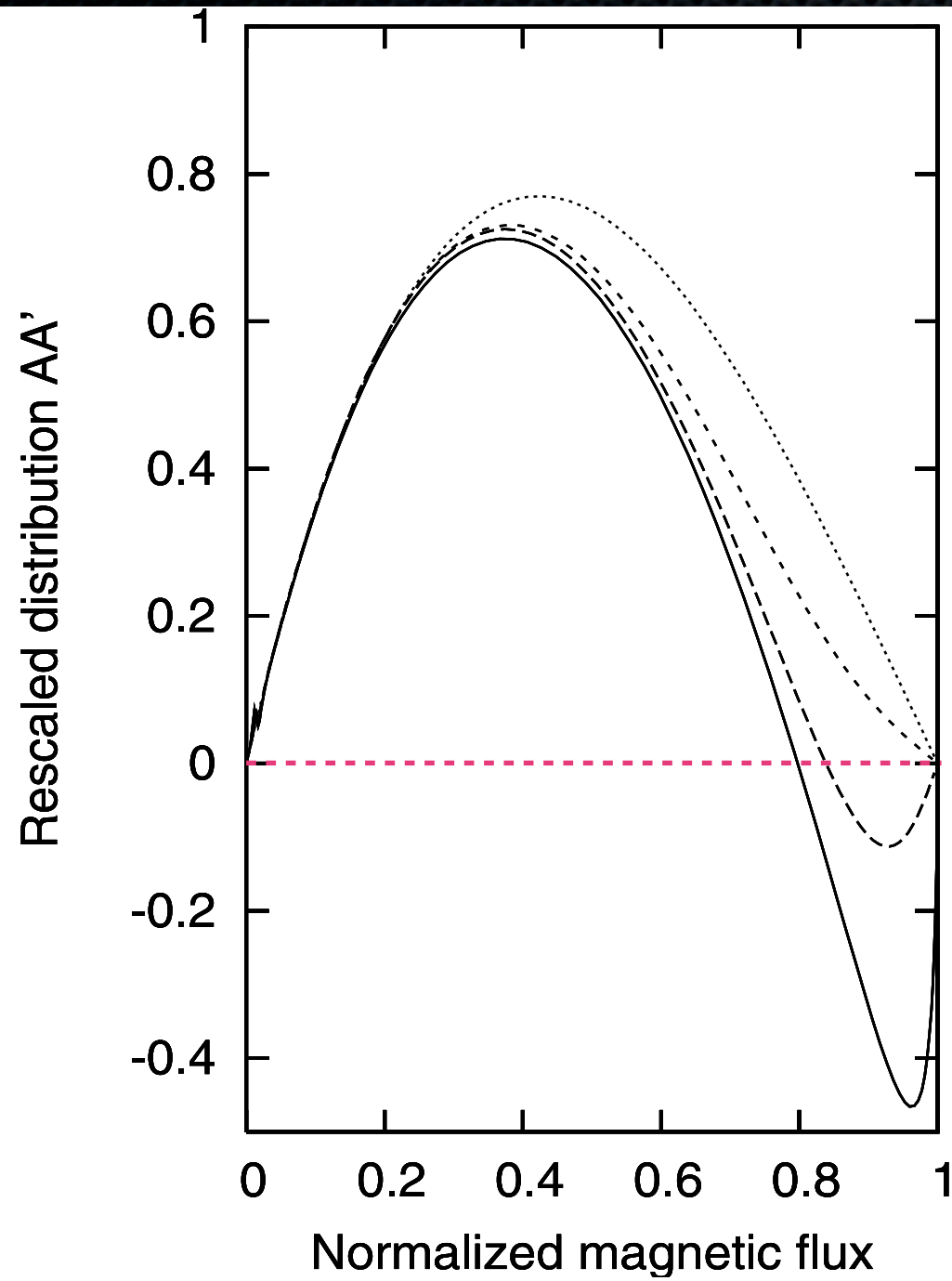


FIG. 1.—Schematic diagram showing the corotating magnetosphere and the wind zone. Star is at lower left.

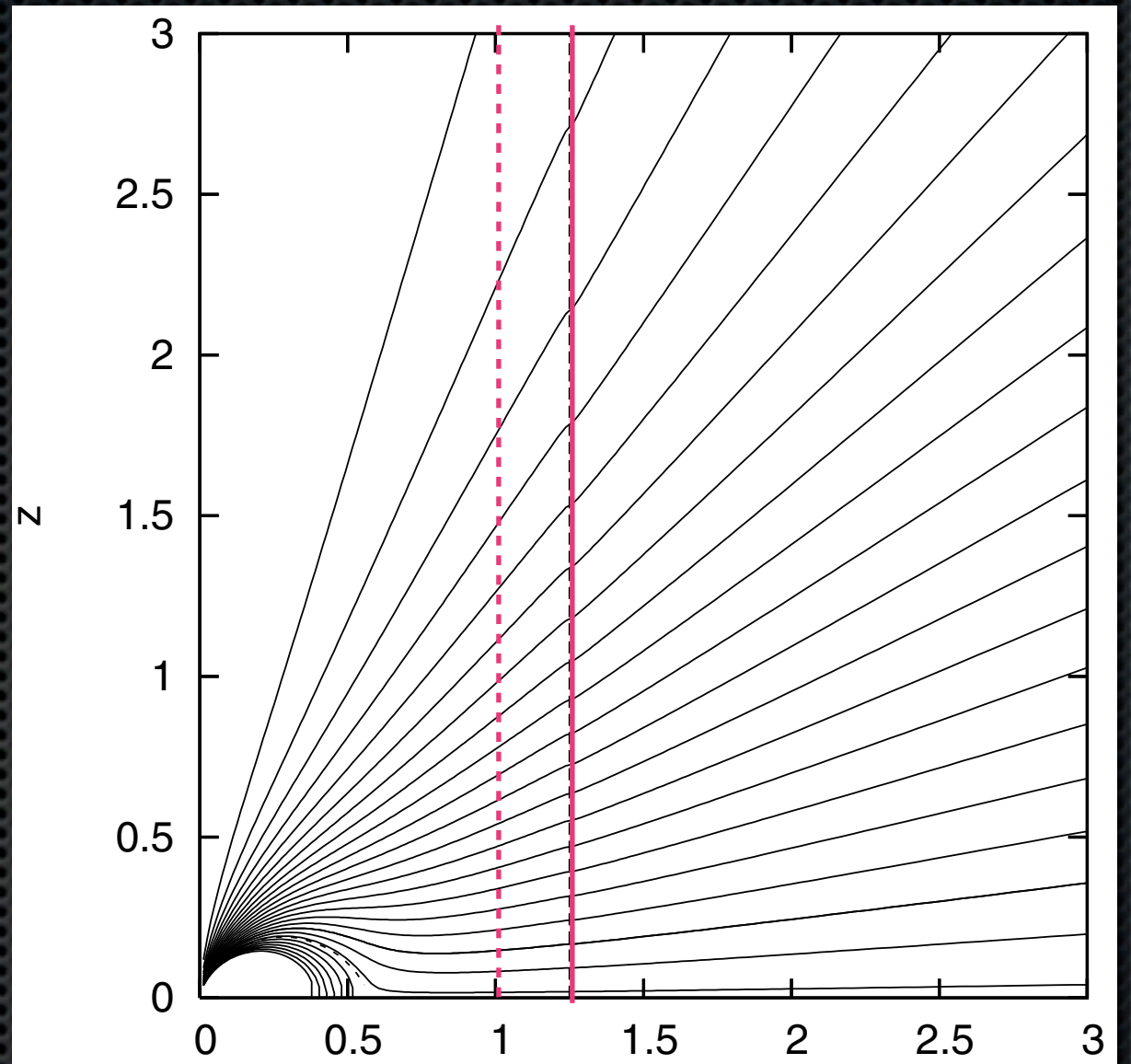
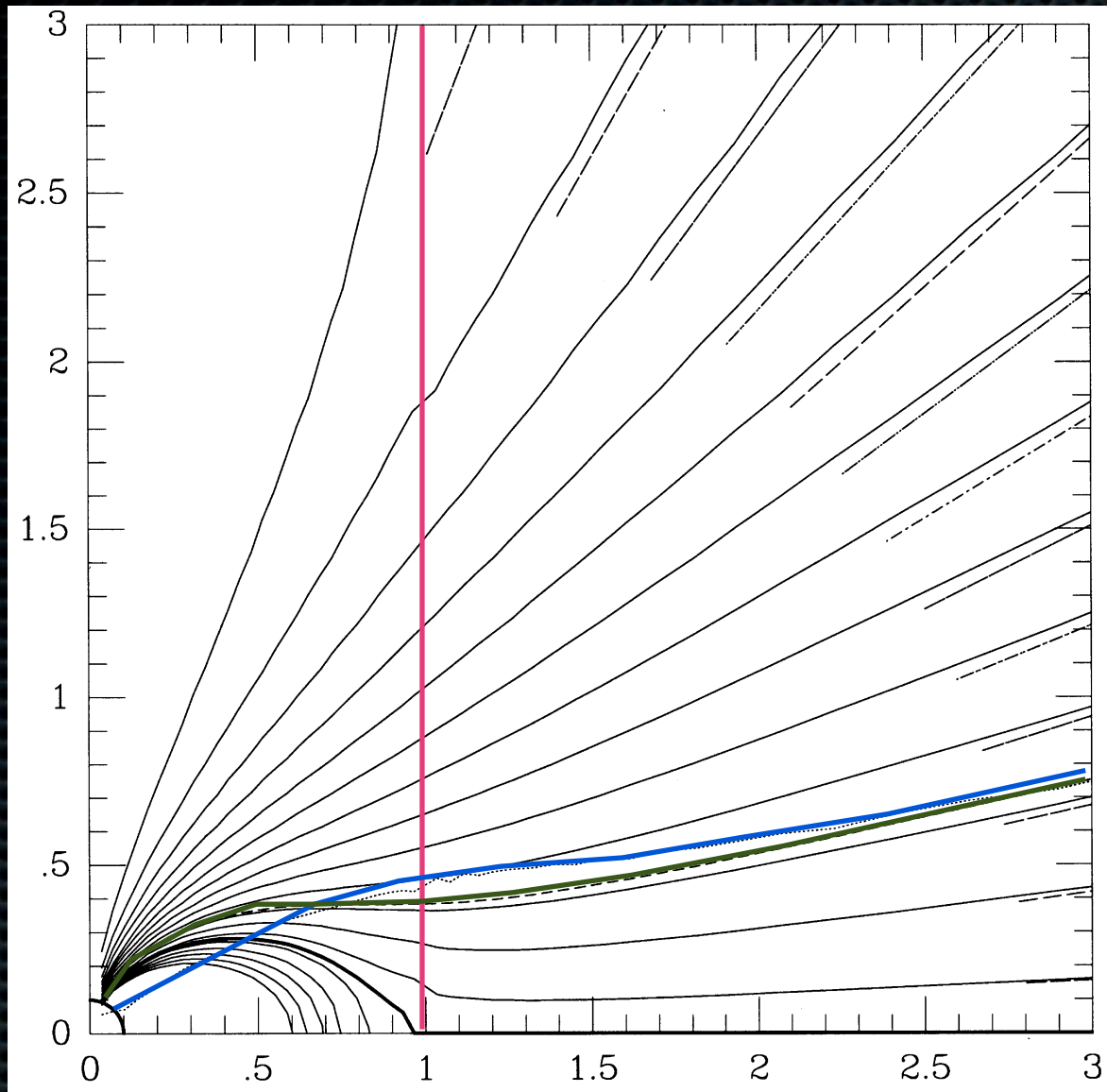
The aligned rotator

Goldreich & Julian 1969



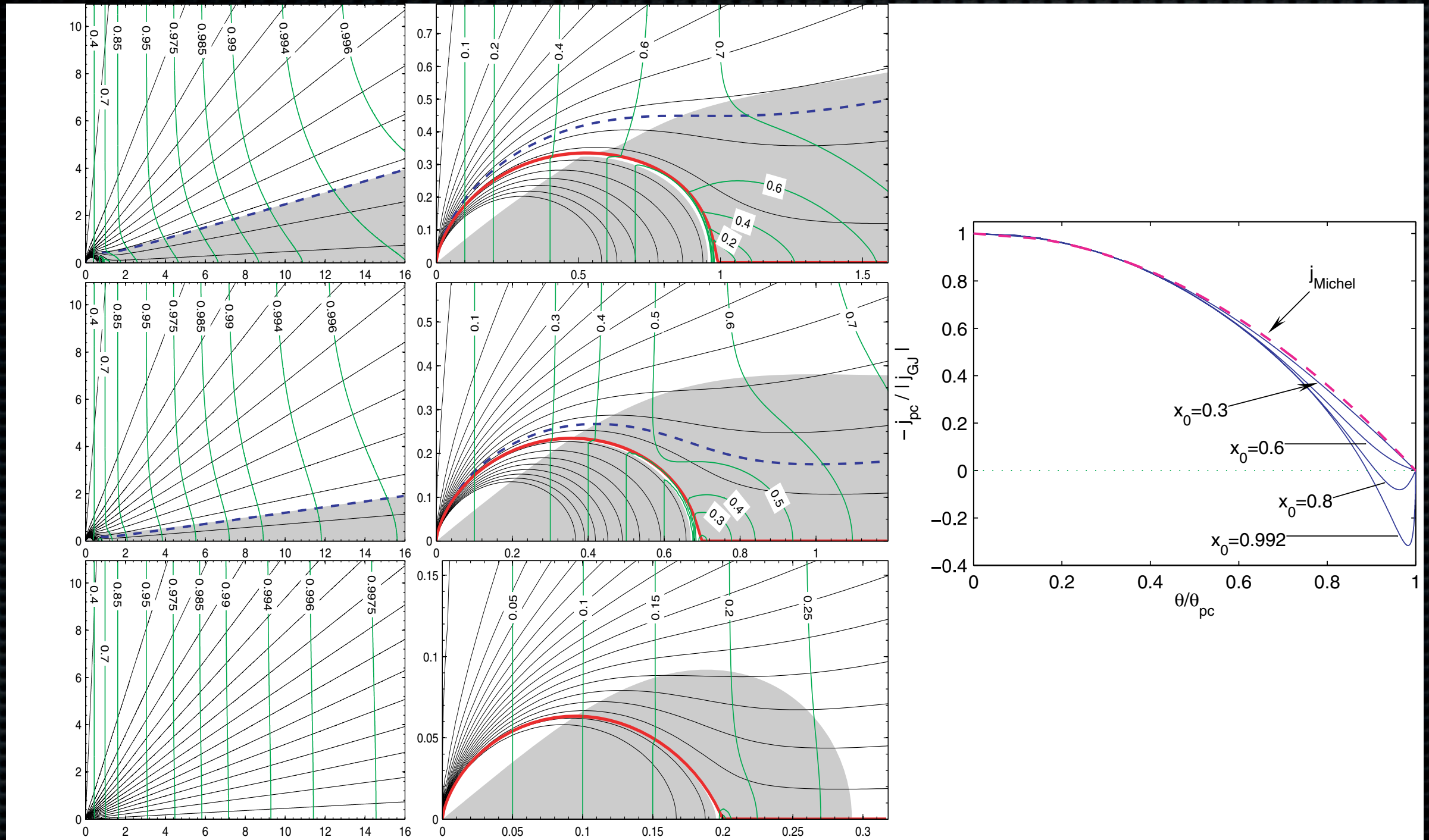


Contopoulos, Kazanas & Fendt 1999
Contopoulos 2005



The aligned rotator

Contopoulos, Kazanas & Fendt 1999



Timokhin 2006

The 3D rotator

- Time-dependent force-free electrodynamics
Gruzinov 1999; Blandford 2002

$$\frac{\partial E}{\partial t} = \nabla \times B - 4\pi J \quad \nabla \cdot B = 0$$

$$\frac{\partial B}{\partial t} = -\nabla \times E \quad E \cdot B = 0$$

$$\rho_e E + J \times B = 0$$

$$J = \rho_e \frac{E \times B}{B^2} + \frac{1}{4\pi} \frac{(B \cdot \nabla \times B - E \cdot \nabla \times E)}{B^2} B$$

The 3D rotator

- Gruzinov 2006

$$V = \Omega \times r$$

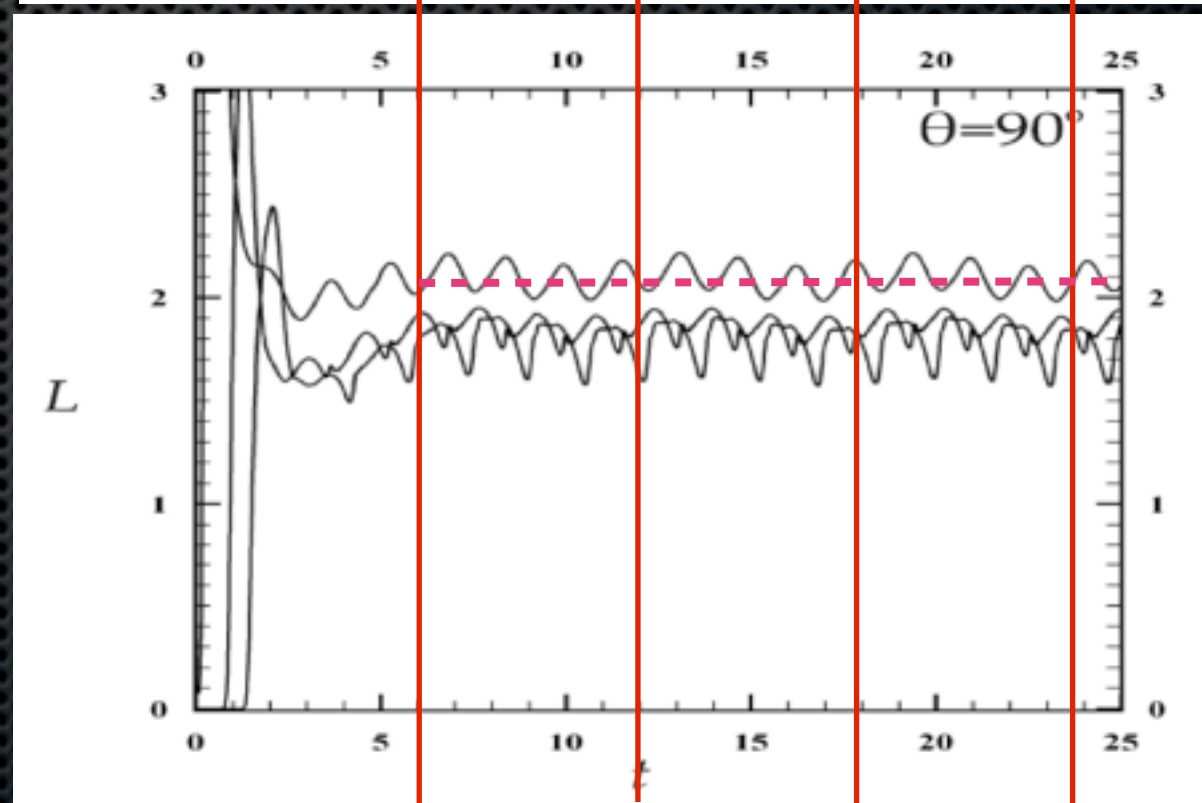
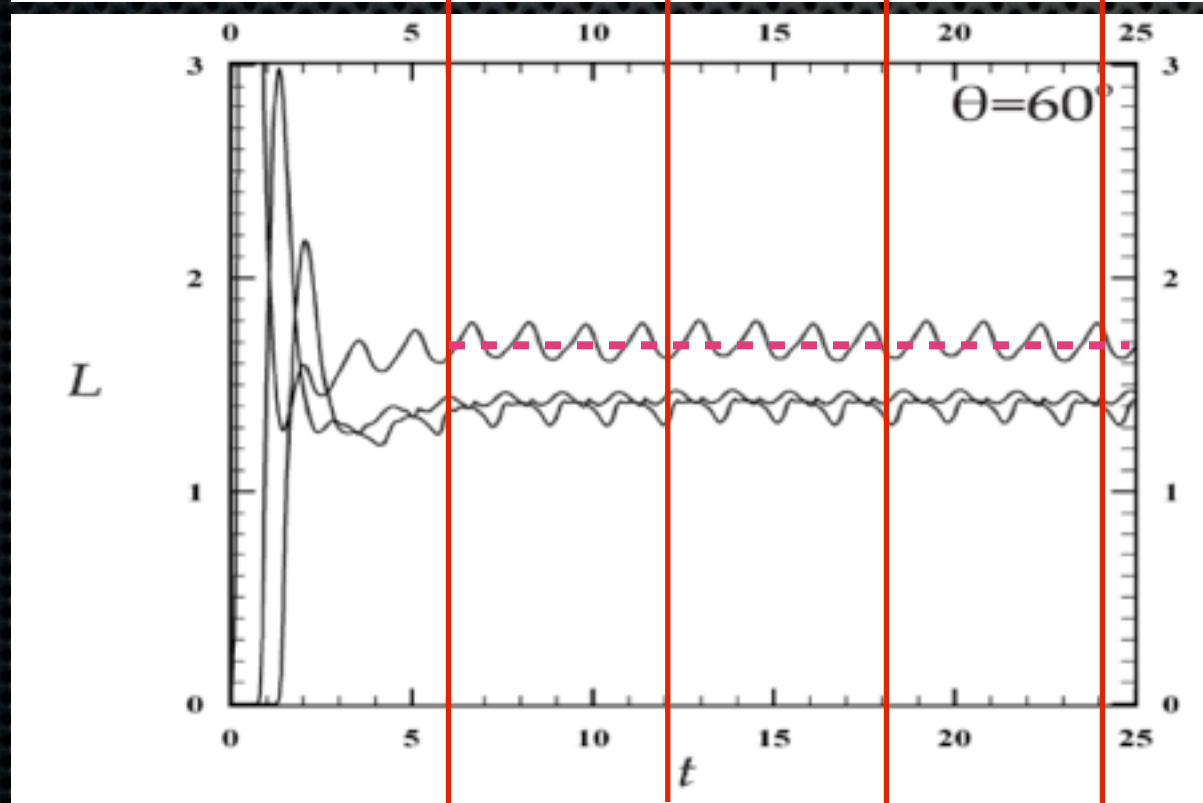
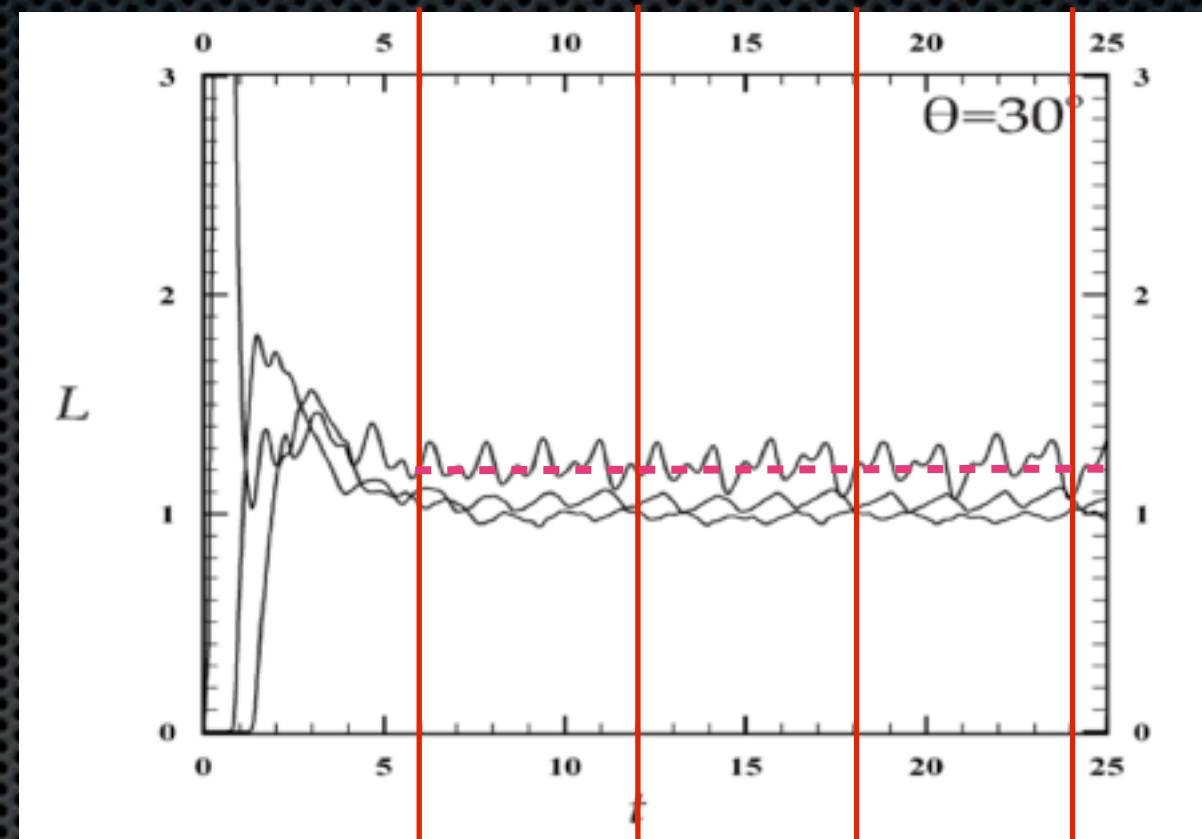
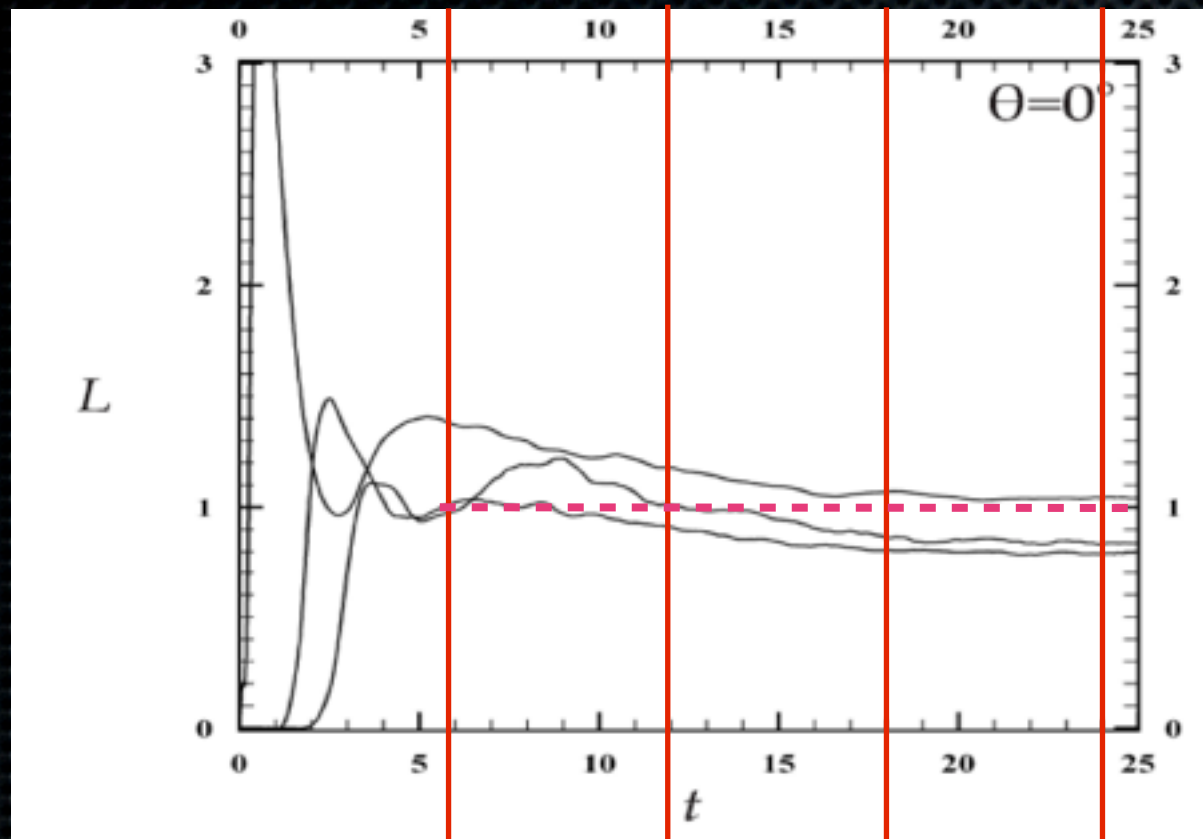
$$E = -V \times B$$

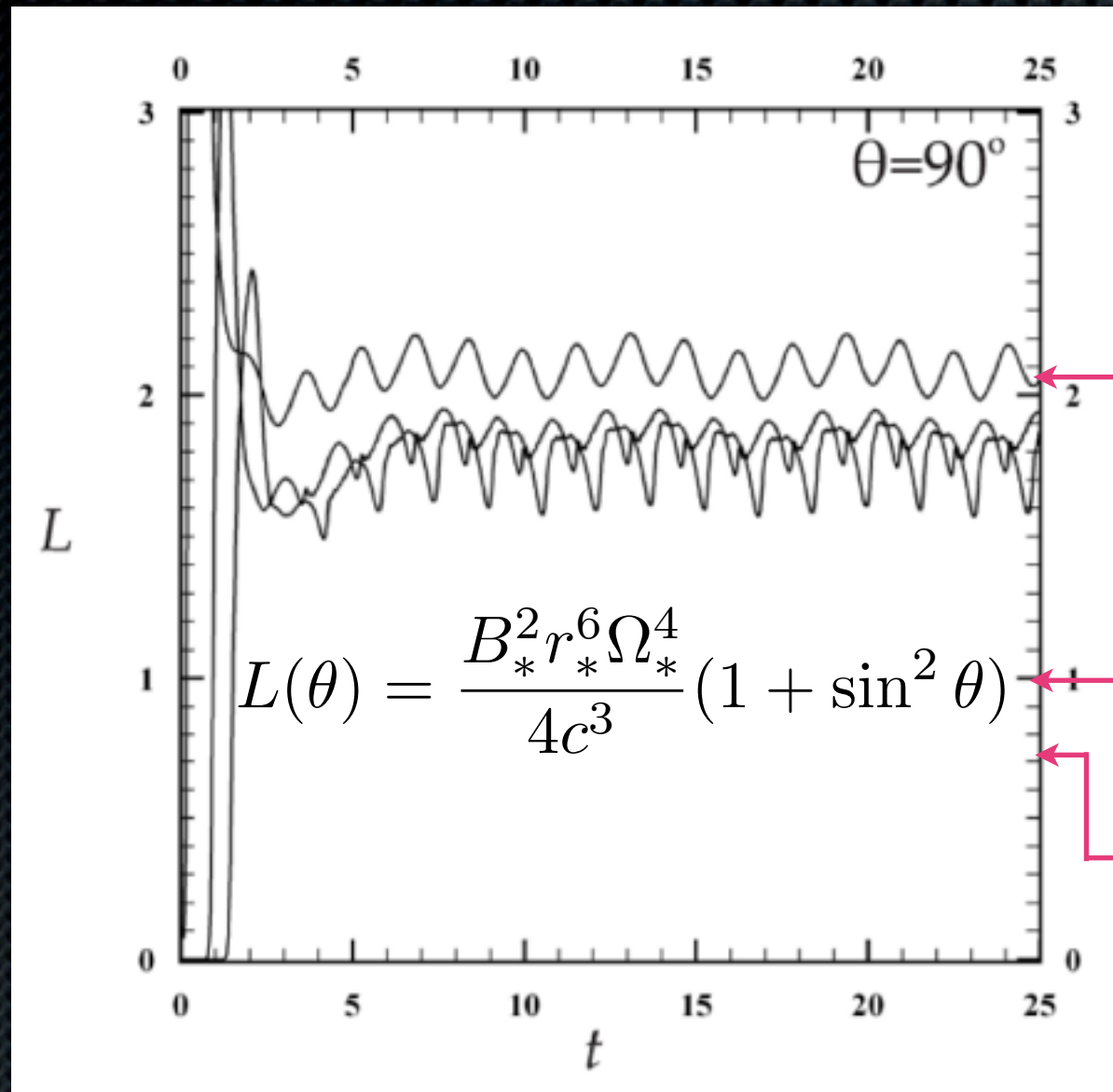
$$\nabla \times (B + V \times (V \times B)) = \lambda B$$

$$\rho_e = \frac{\nabla \cdot E}{4\pi} = -\frac{\Omega \cdot B}{2\pi c} + \frac{V \cdot (\nabla \times B)}{4\pi}$$

The 3D rotator

- ✦ Staggered cartesian mesh ($\delta=0.025R_{lc}$)
- ✦ Finite difference time domain (Yee 1966)
- ✦ Non-reflecting absorbing boundaries (PML)
- ✦ We impose the conditions $E \perp B$ and $E < B$





FFE orthogonal rotator

Aligned rotator

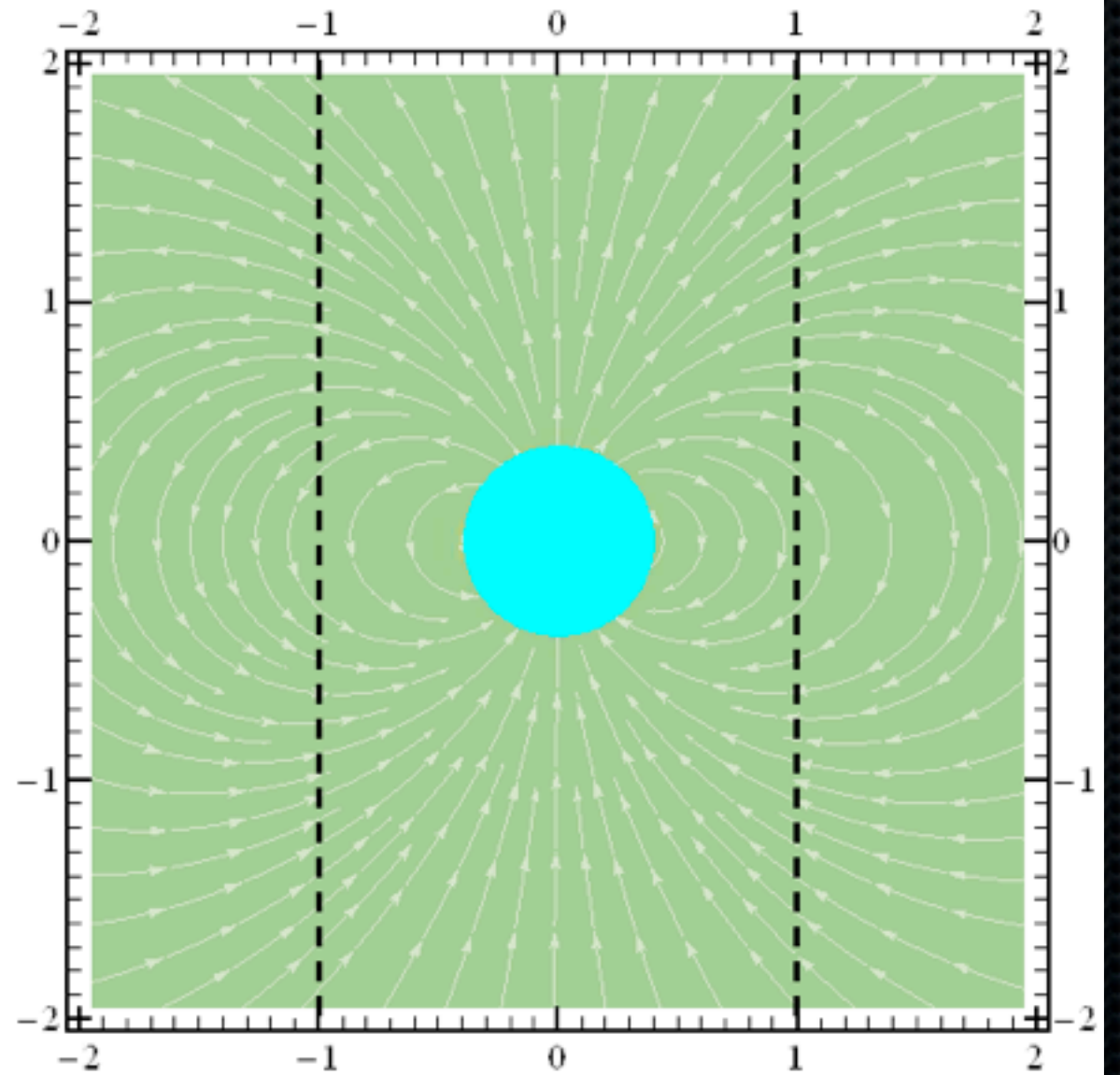
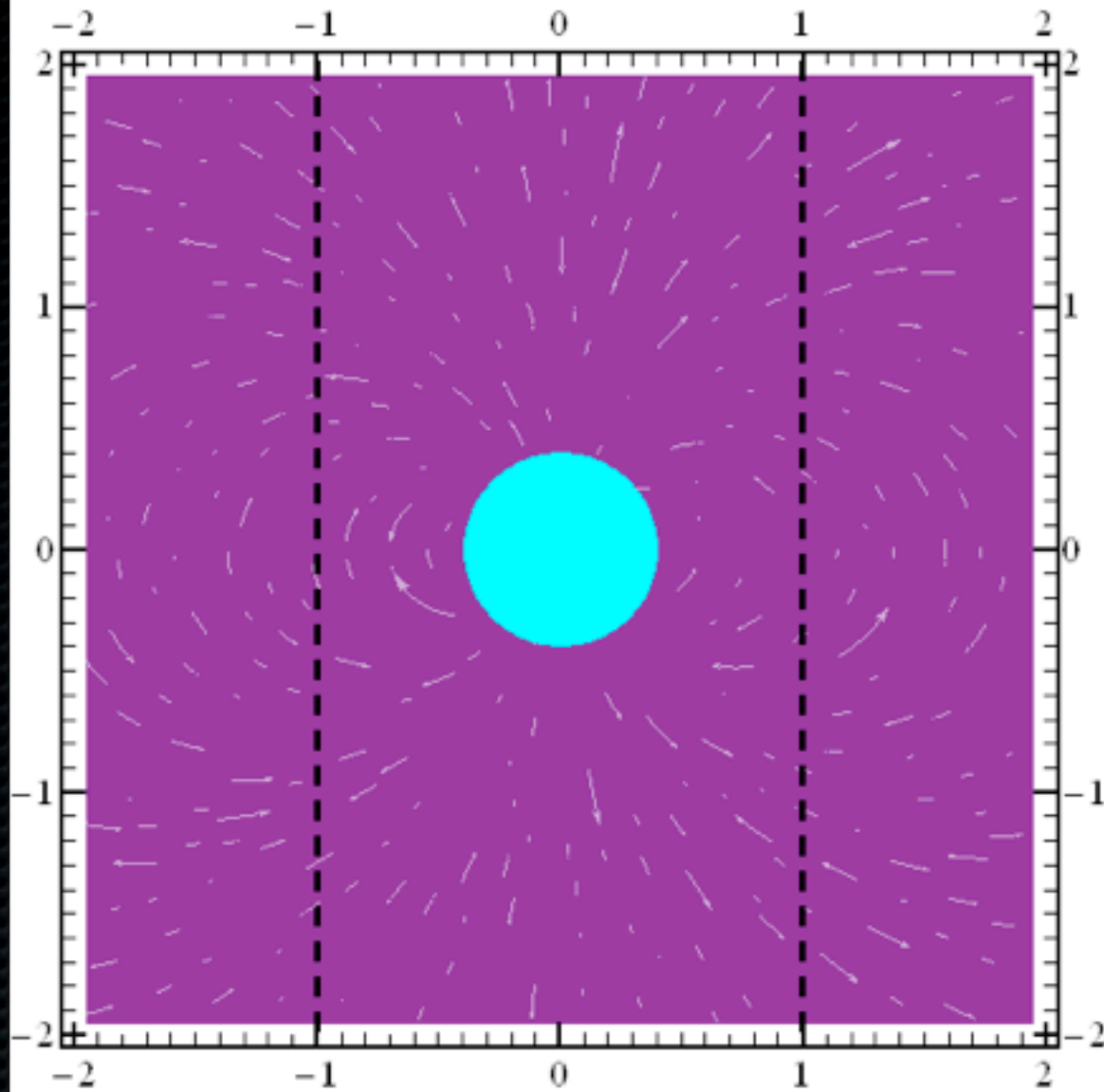
Vacuum orthogonal rotator

FFE orthogonal rotator

Spitkovsky 2006

Kalapothisarakos & Contopoulos 2009

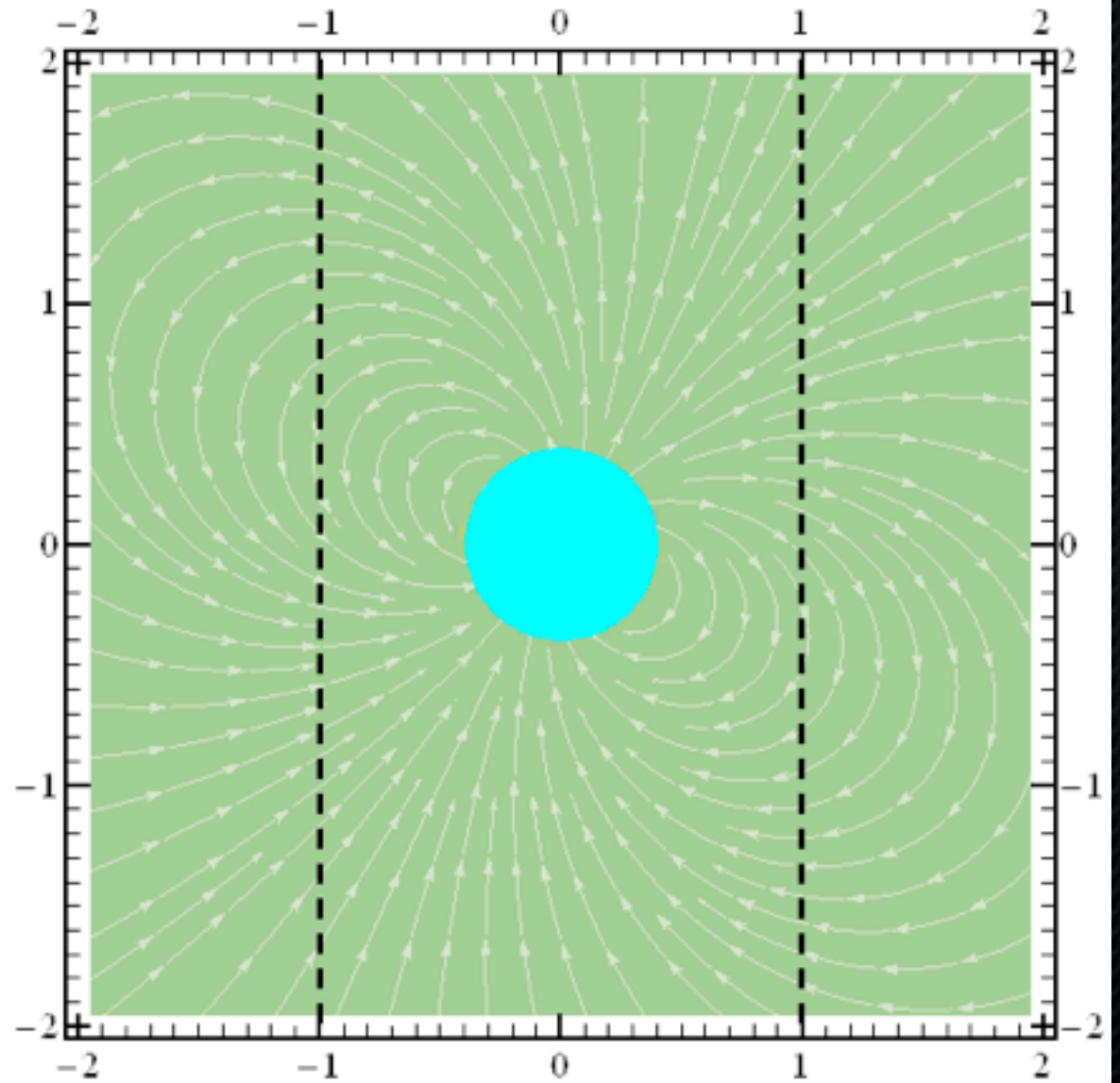
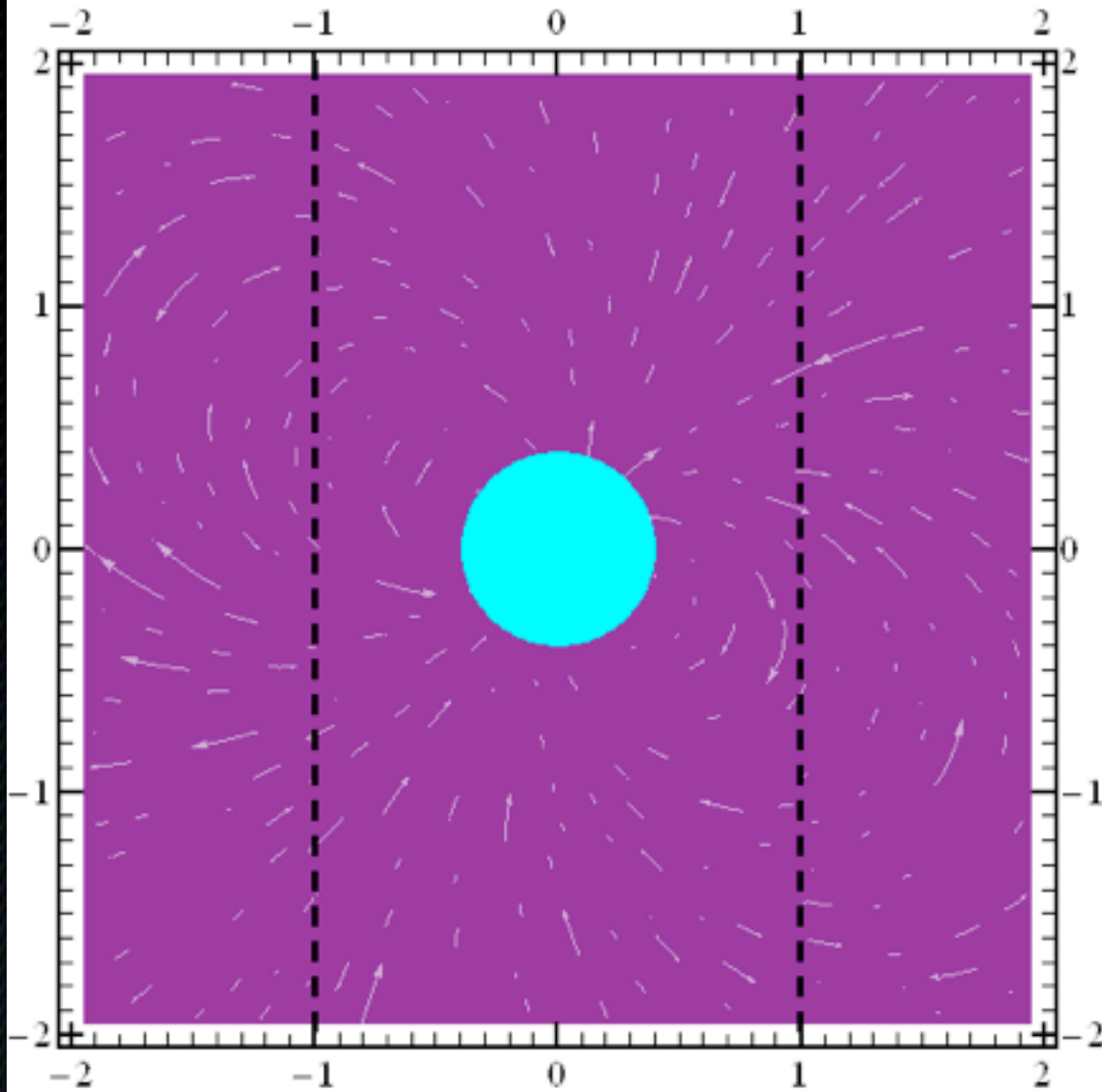
$t=0$



Aligned rotator

Contopoulos & Kalapotharakos 2010

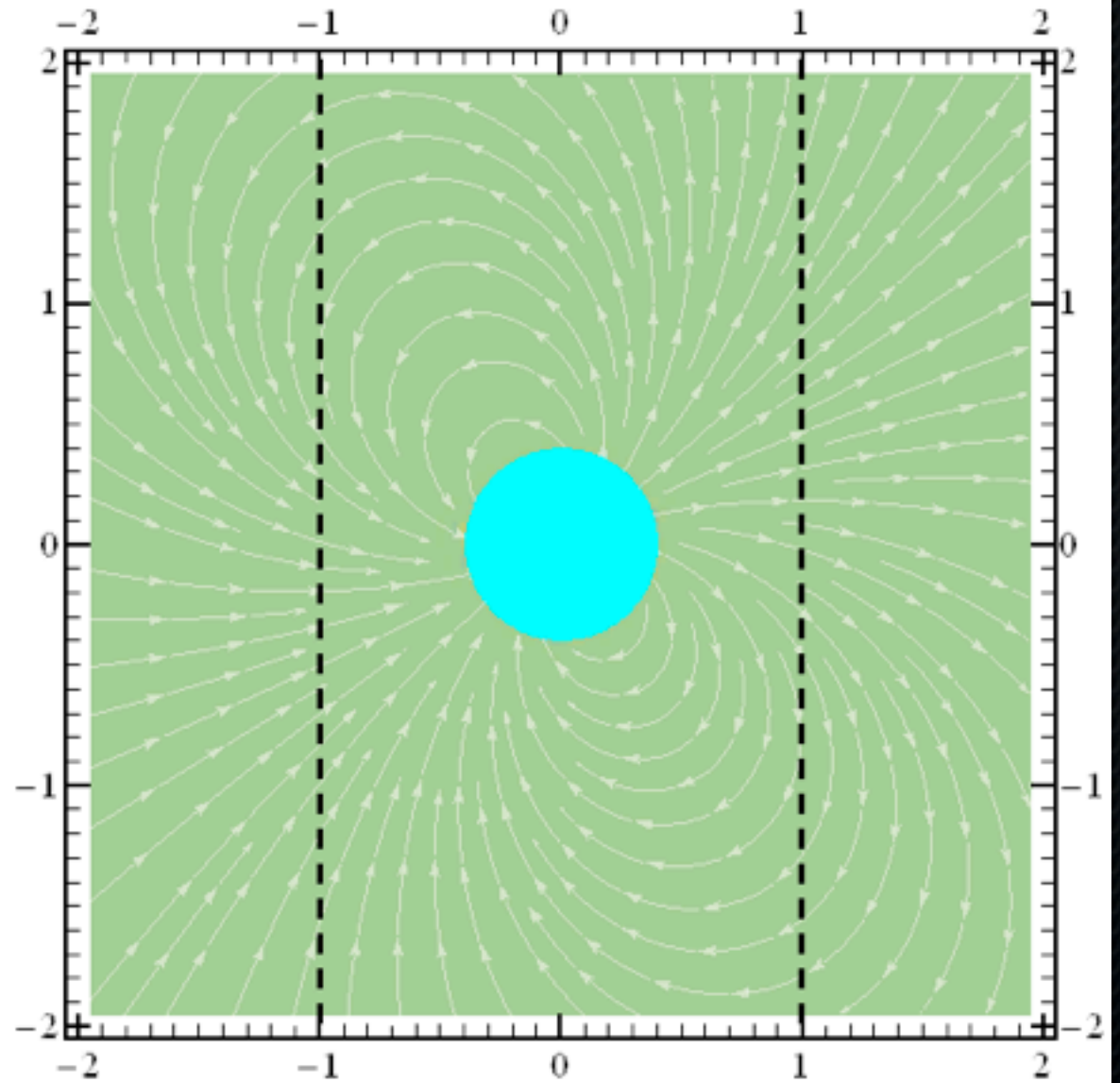
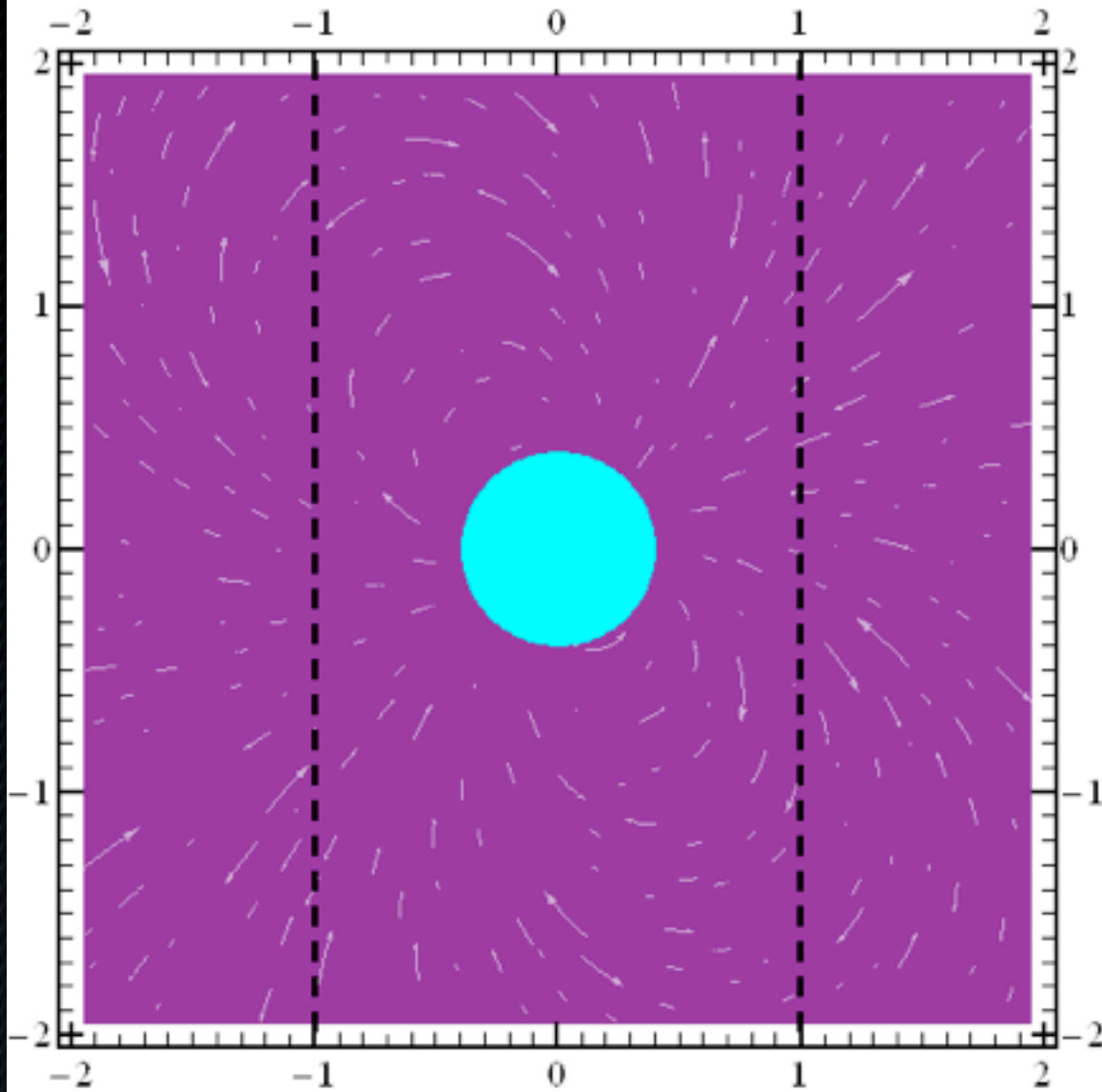
$t=0$



30° inclination

Contopoulos & Kalapotharakos 2010

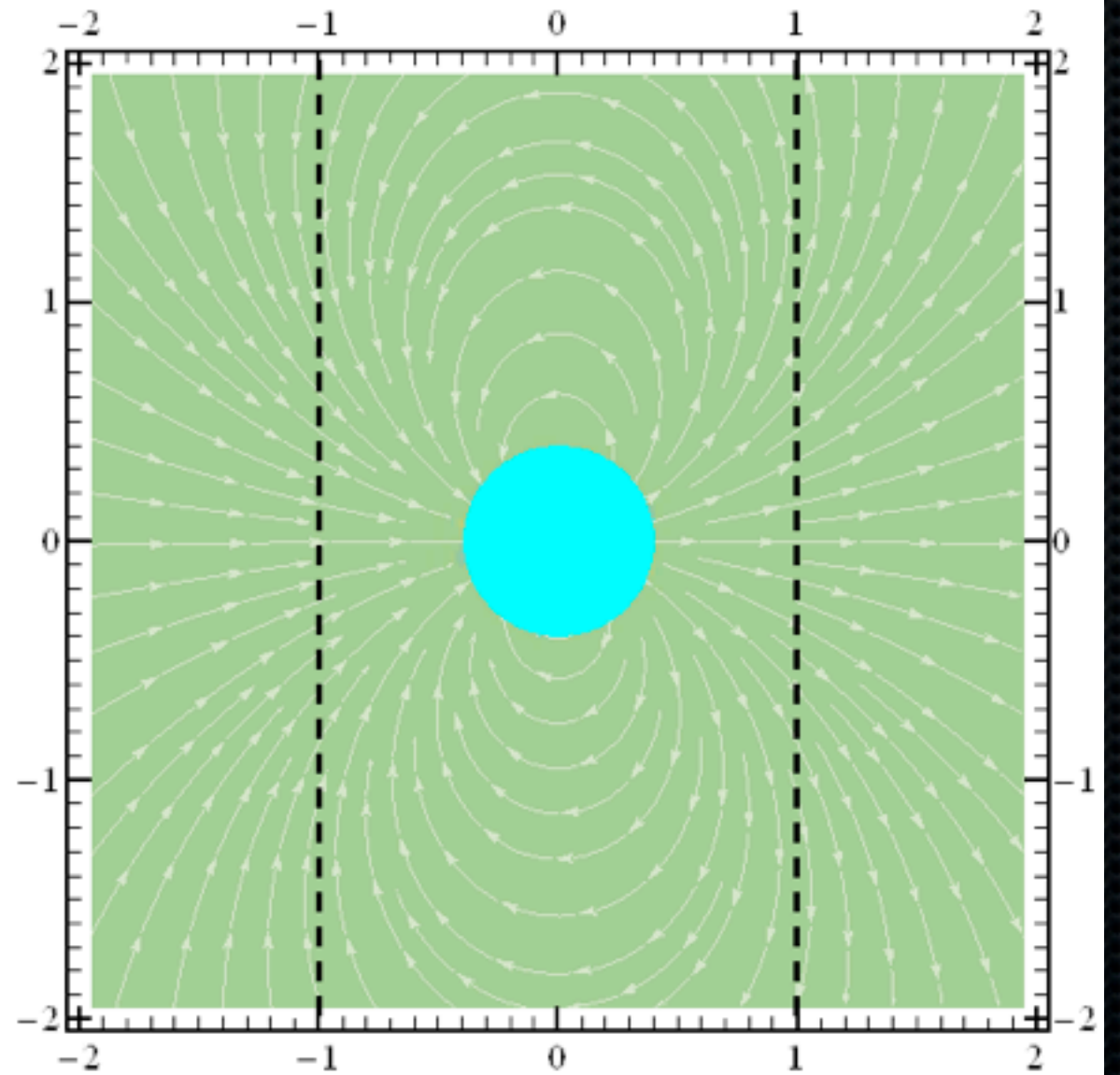
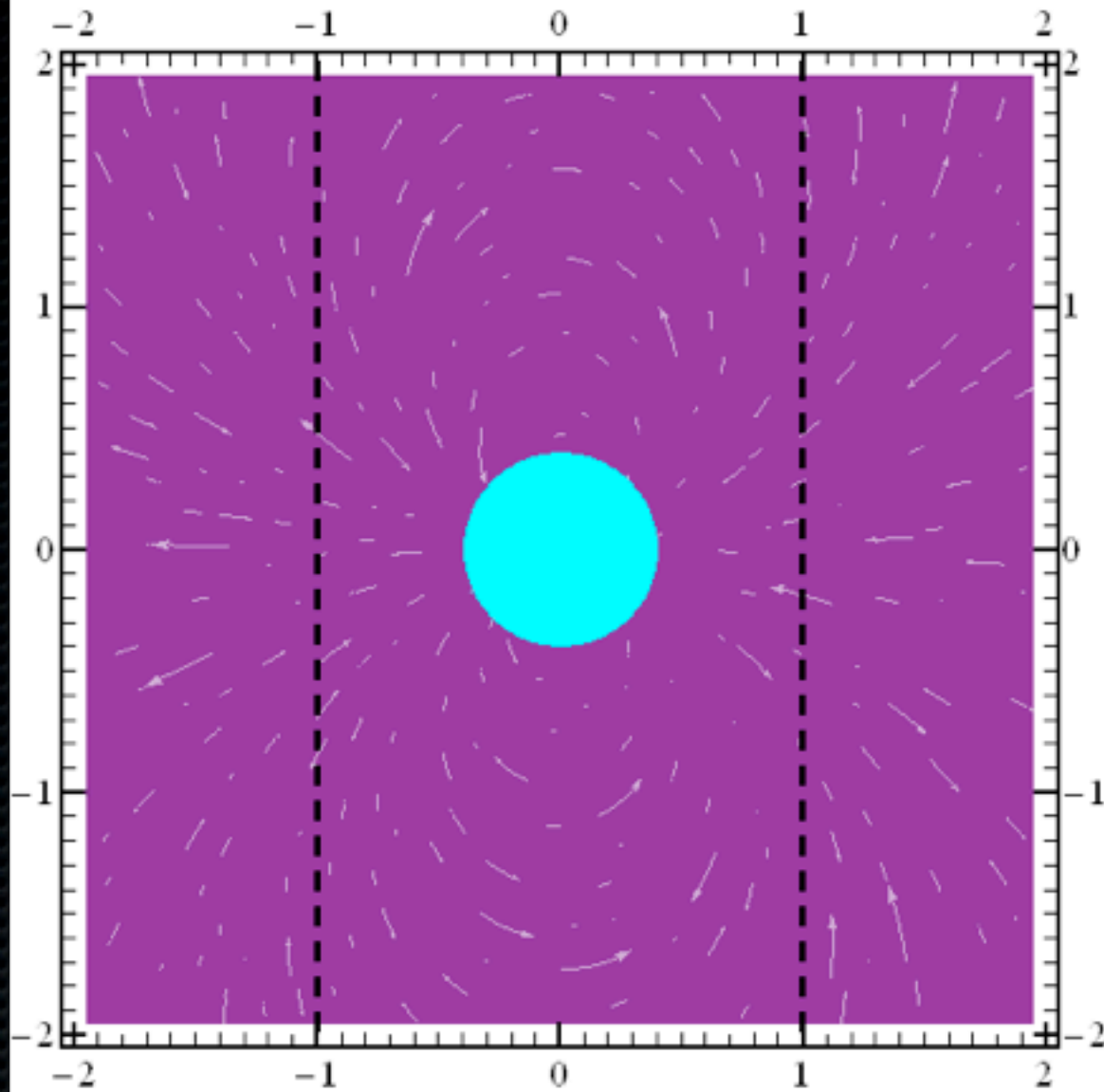
$t=0$



60° inclination

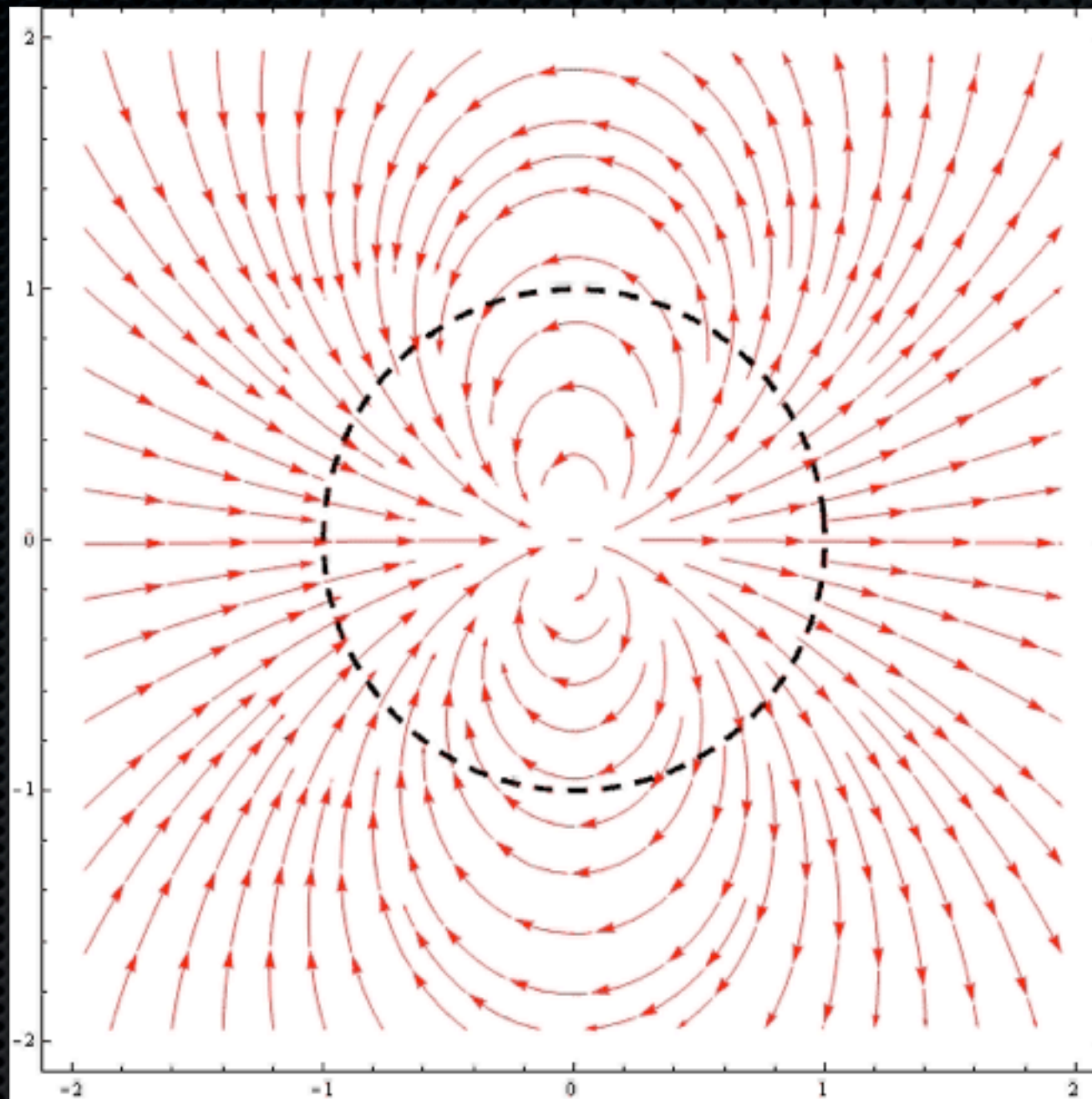
Contopoulos & Kalapotharakos 2010

$t=0$



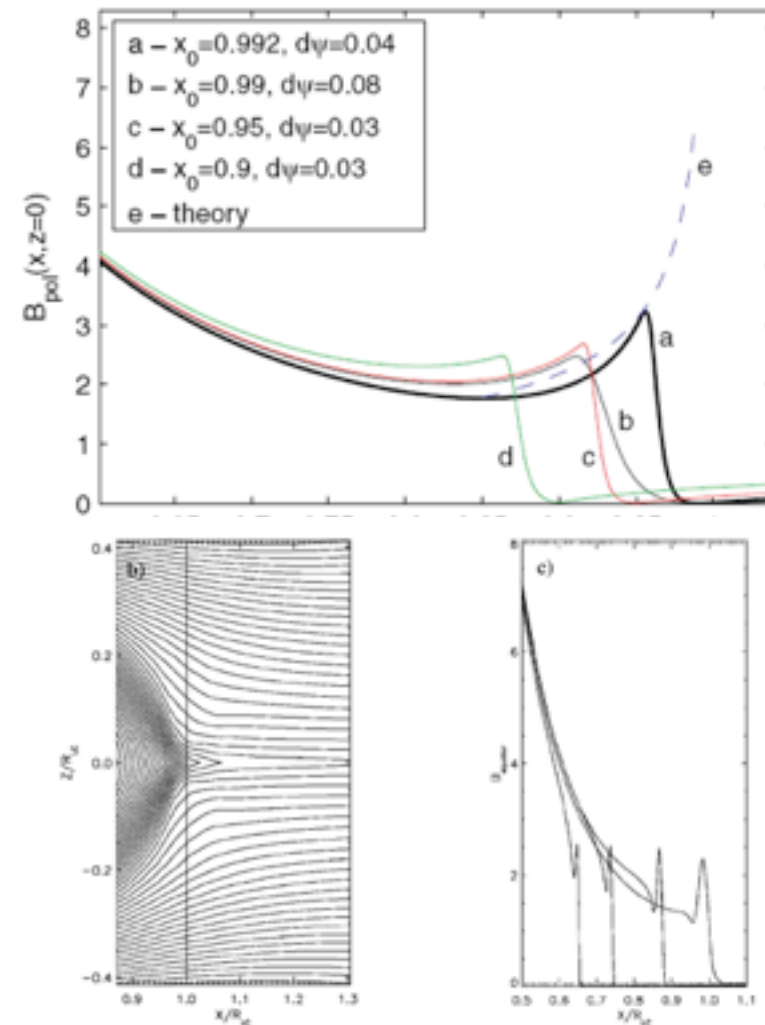
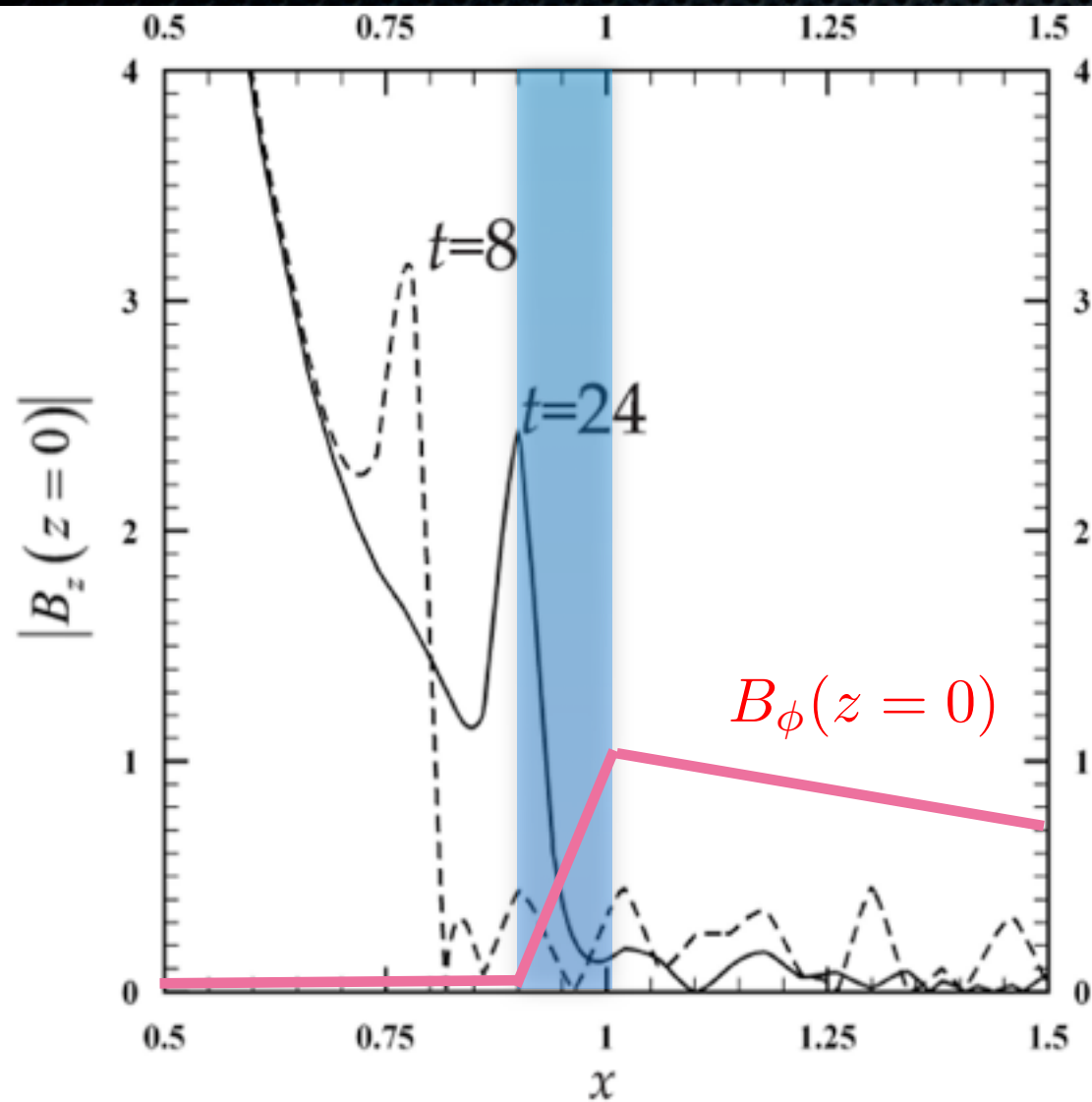
Orthogonal rotator

Contopoulos & Kalapotharakos 2010



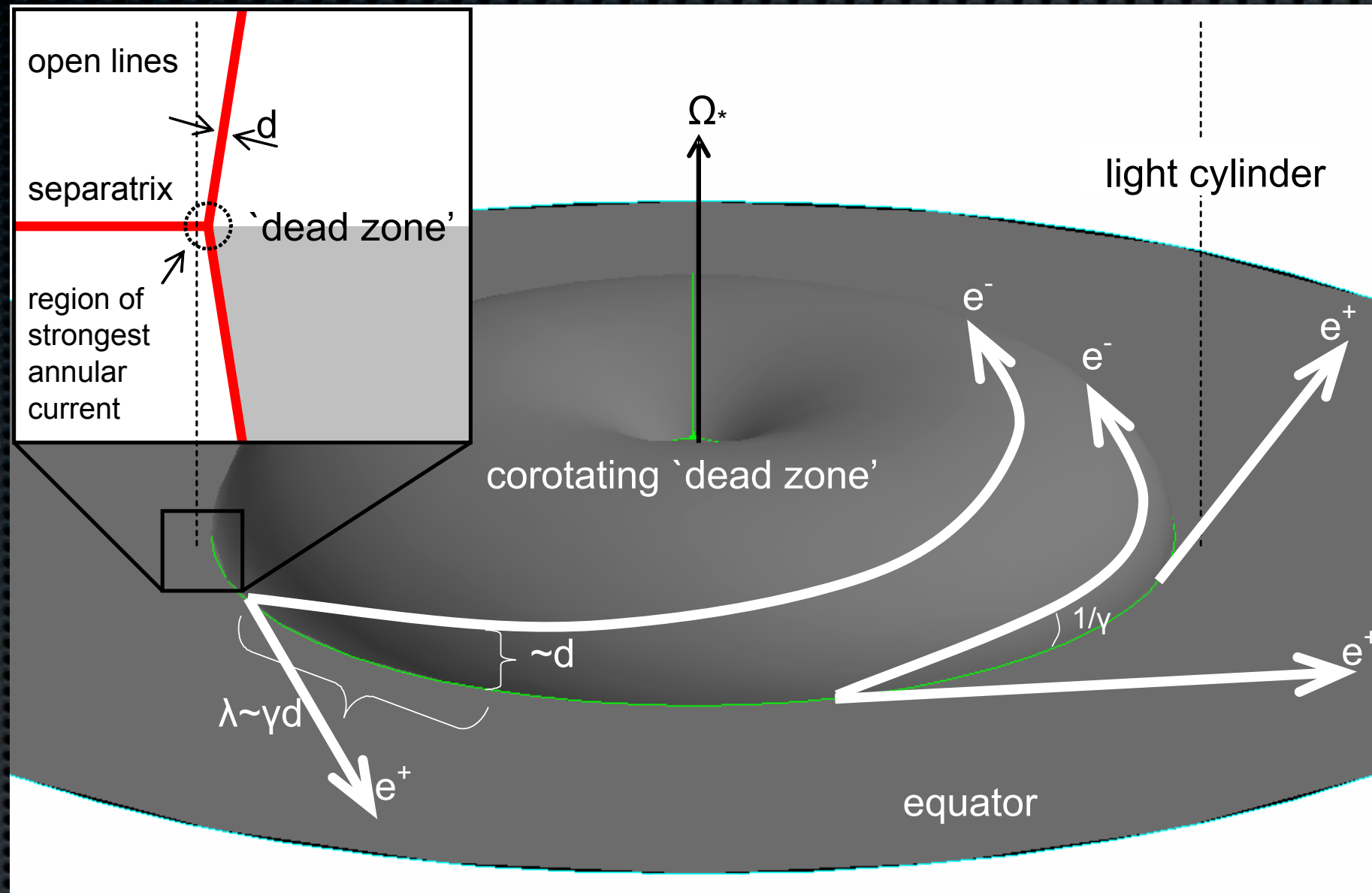
Orthogonal rotator

Contopoulos & Kalapotharakos 2010



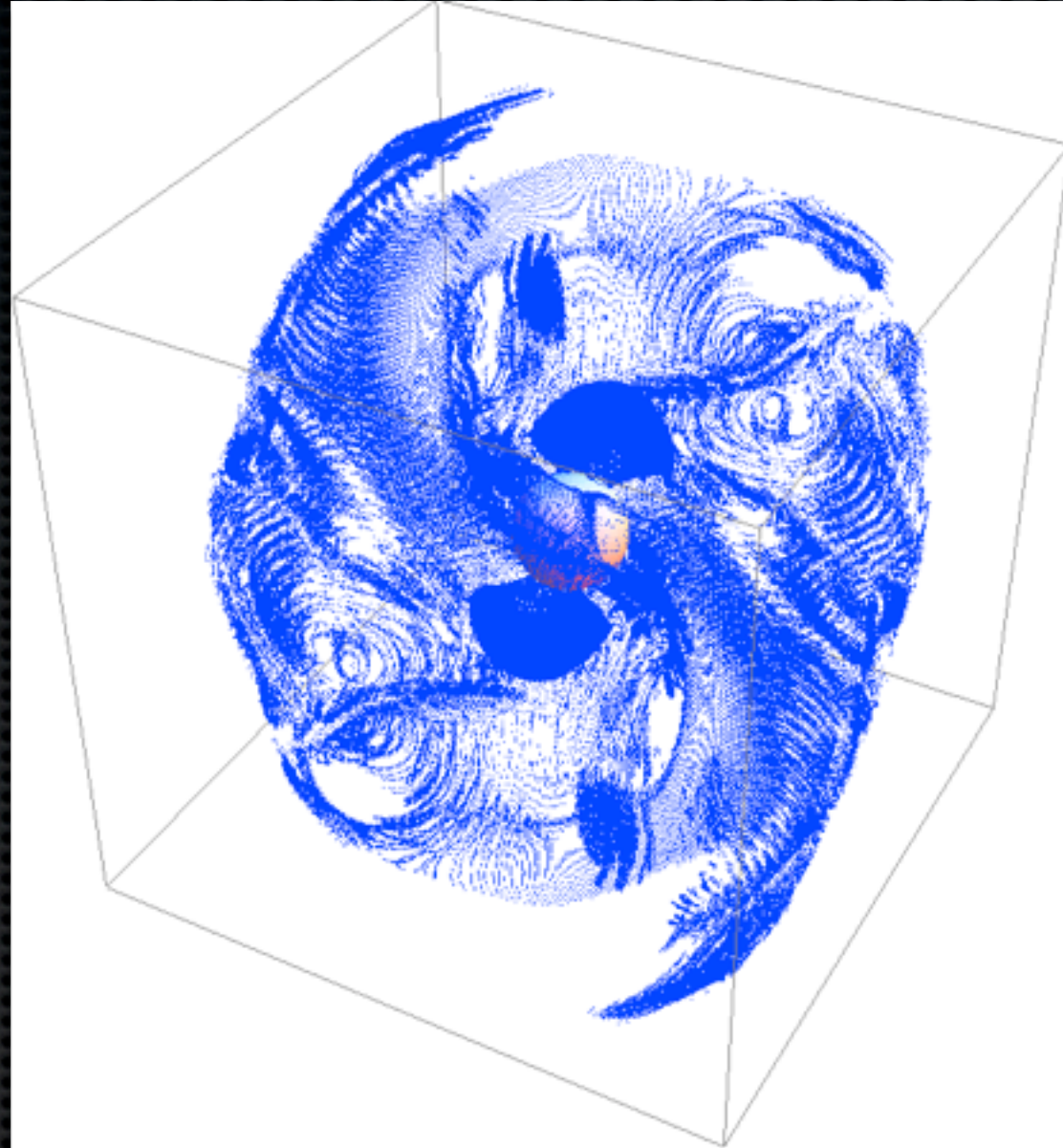
The aligned rotator

Kalapothisarakos & Contopoulos 2009



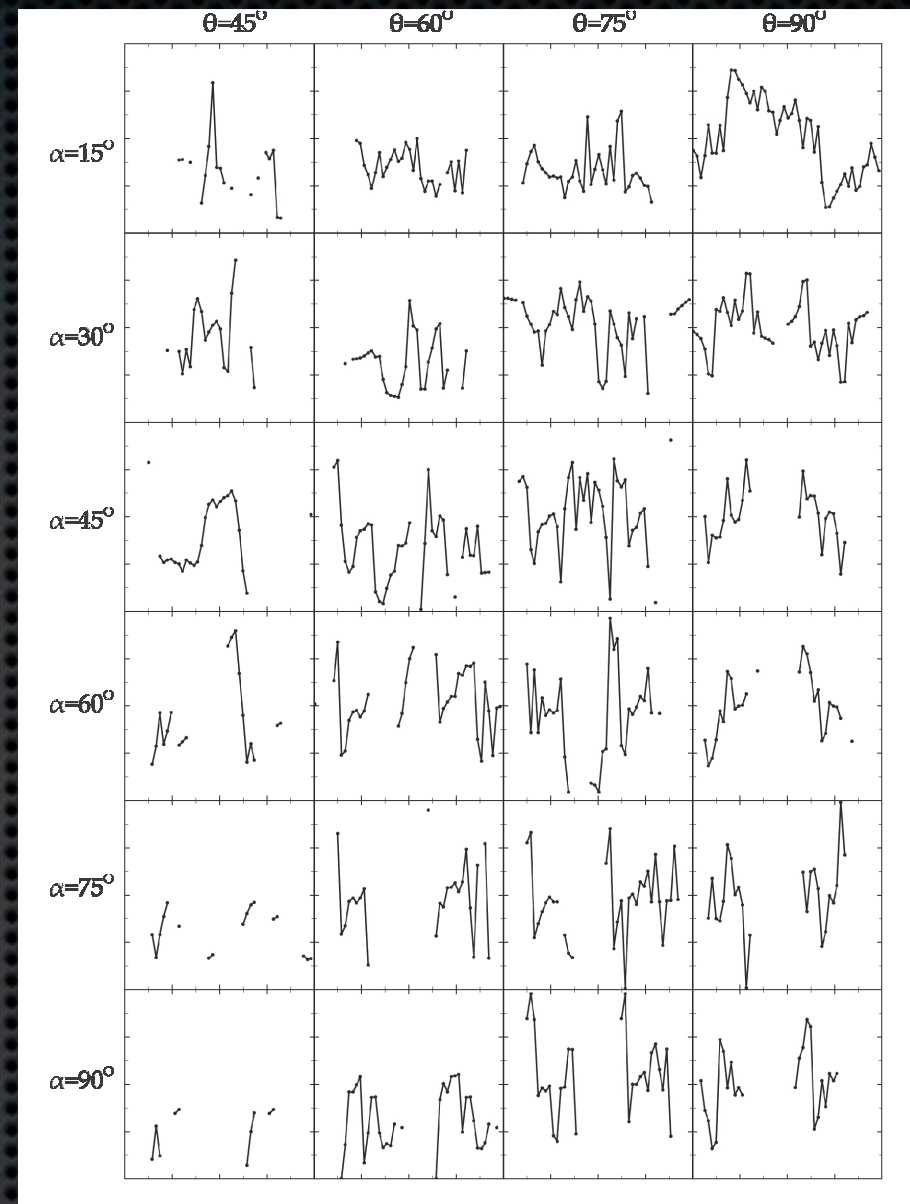
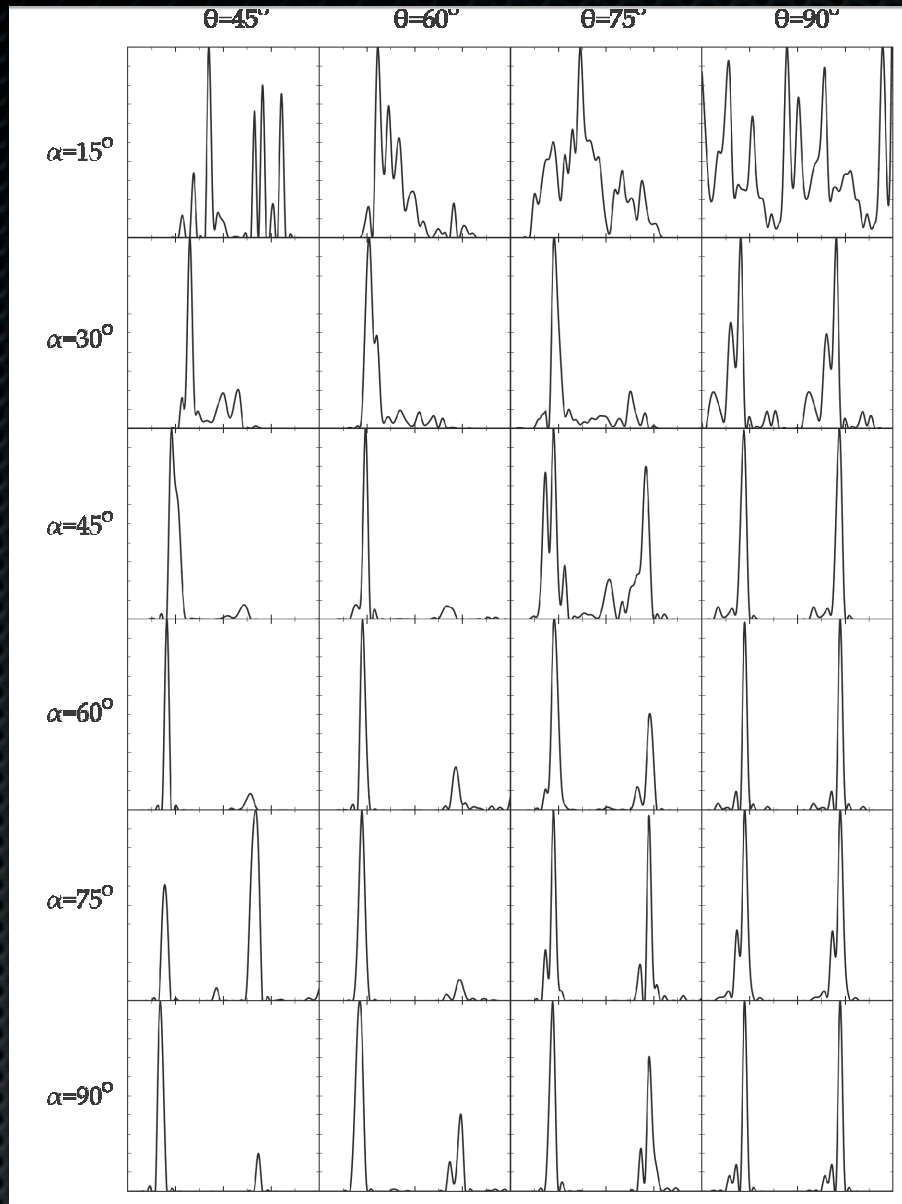
Equatorial current sheet

Contopoulos 2009



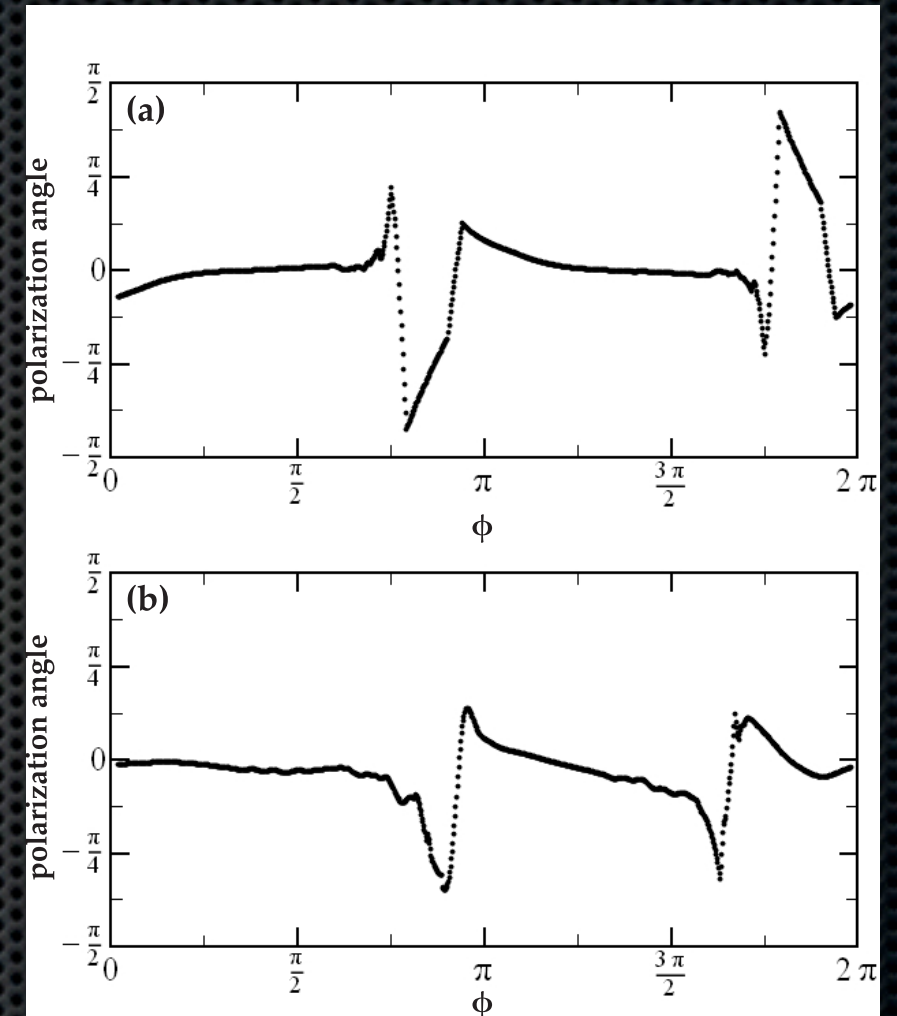
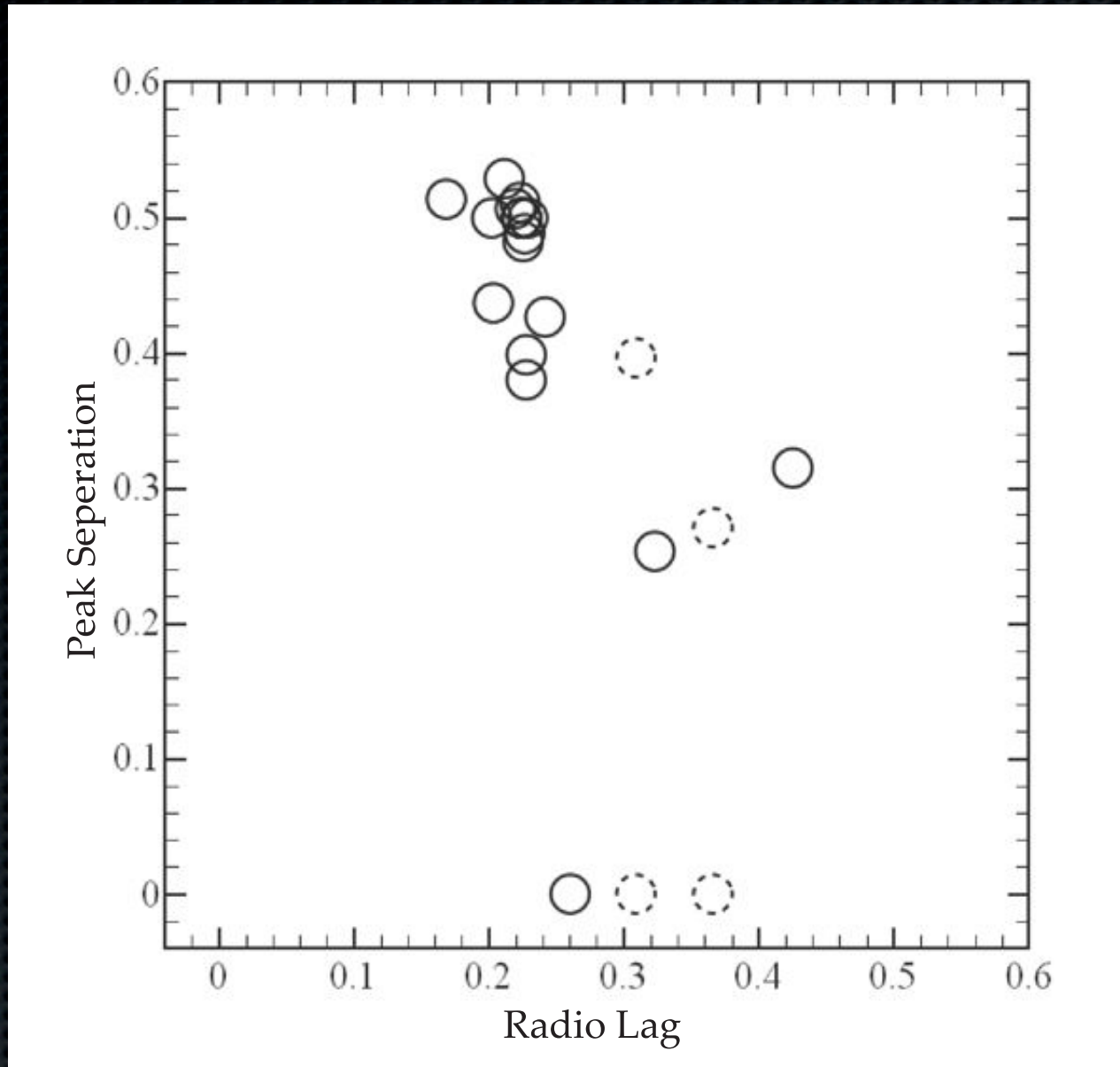
Equatorial current sheet

Contopoulos & Kalapotharakos 2010



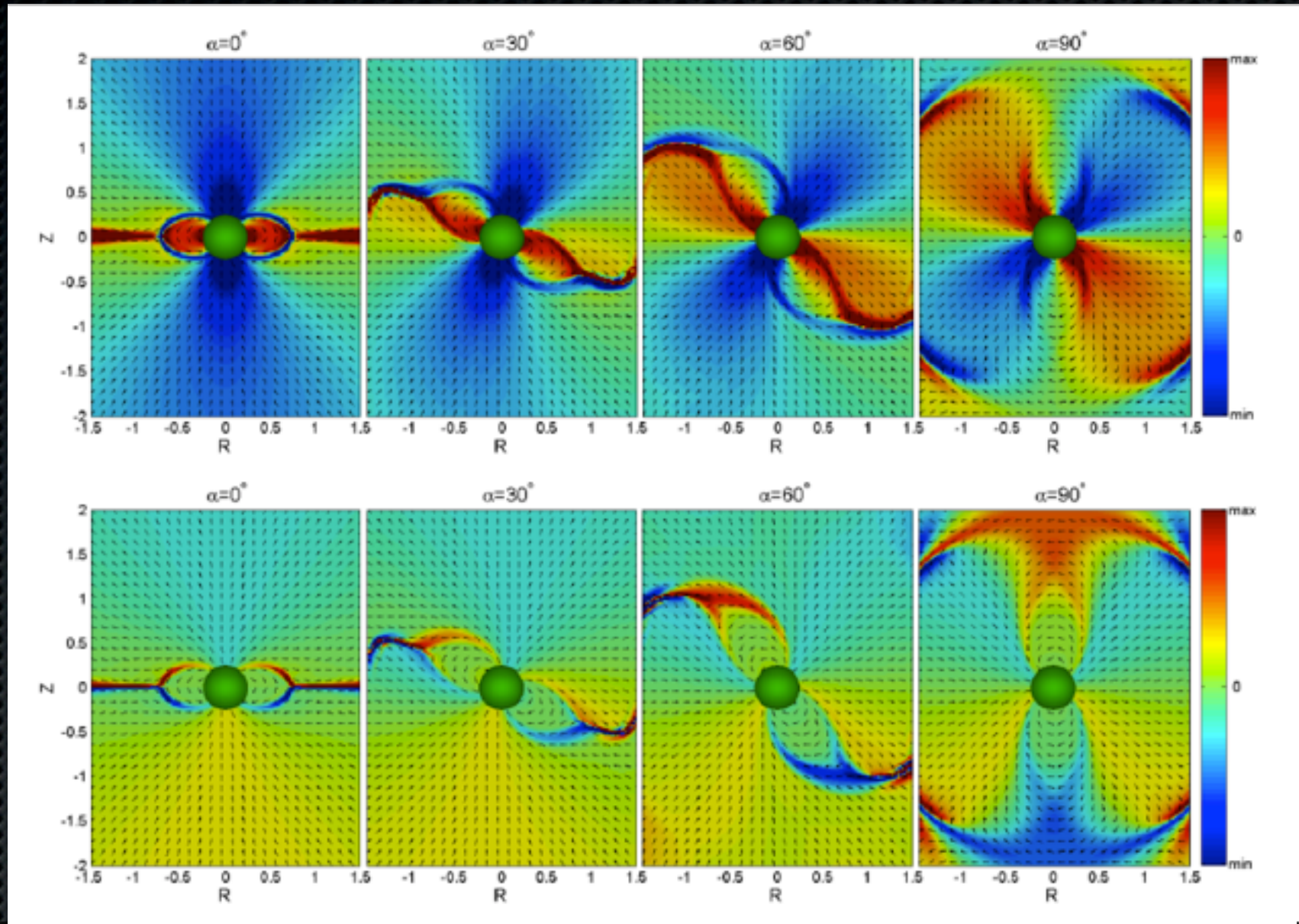
3D rotator

Contopoulos & Kalapotharakos 2010



3D rotator

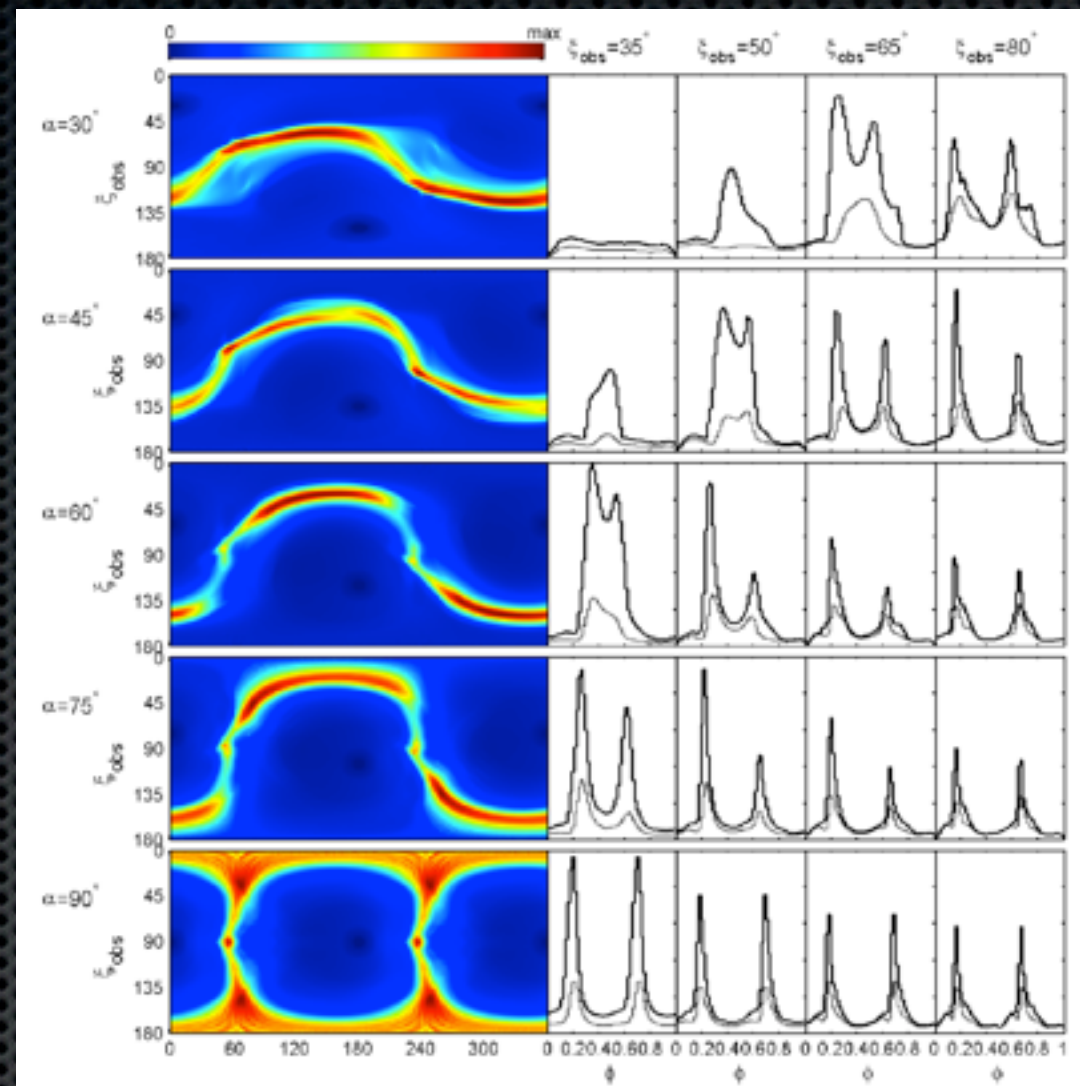
Contopoulos & Kalapotharakos 2010



3D rotator

Bai & Spitkovsky 2010

Spitkovsky 2006



3D rotator

Bai & Spitkovsky 2010

Prospects for the future

- ✦ Parallelize code to run on ~ 1000 CPUs
 - ✦ Higher grid resolution ($\delta = 0.0025 R_{lc}$)
 - ✦ Extended integration region
- ✦ Adaptive Mesh Refinement (AMR) on current sheet
- ✦ Relax force-free assumption
 - ✦ Singular regions with $E \parallel B$
 - ✦ Include radiation reaction
- ✦ Relax ideal MHD condition
 - ✦ Reconnection in equatorial current sheet

